



**CHALLENGES
IN EUROPEAN
AEROSPACE**
5TH CEAS AIR & SPACE CONFERENCE



Academic Course in Aircraft conceptual design and on-board system preliminary design at Politecnico di Torino

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**POLITECNICO
DI TORINO**



Course title: Integrated Aerospace Systems Design

When: 2nd year of Master degree

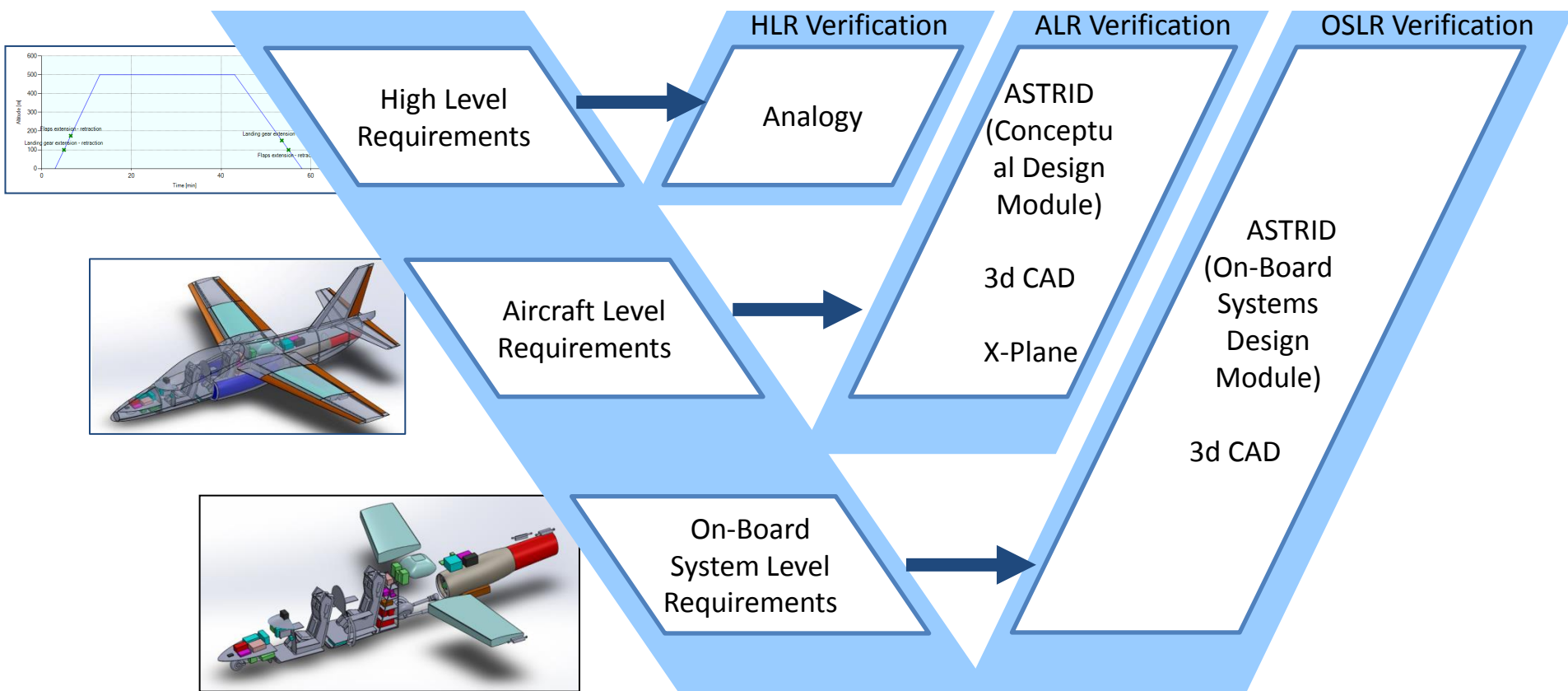
Who: 25 – 30 students and 4 teachers

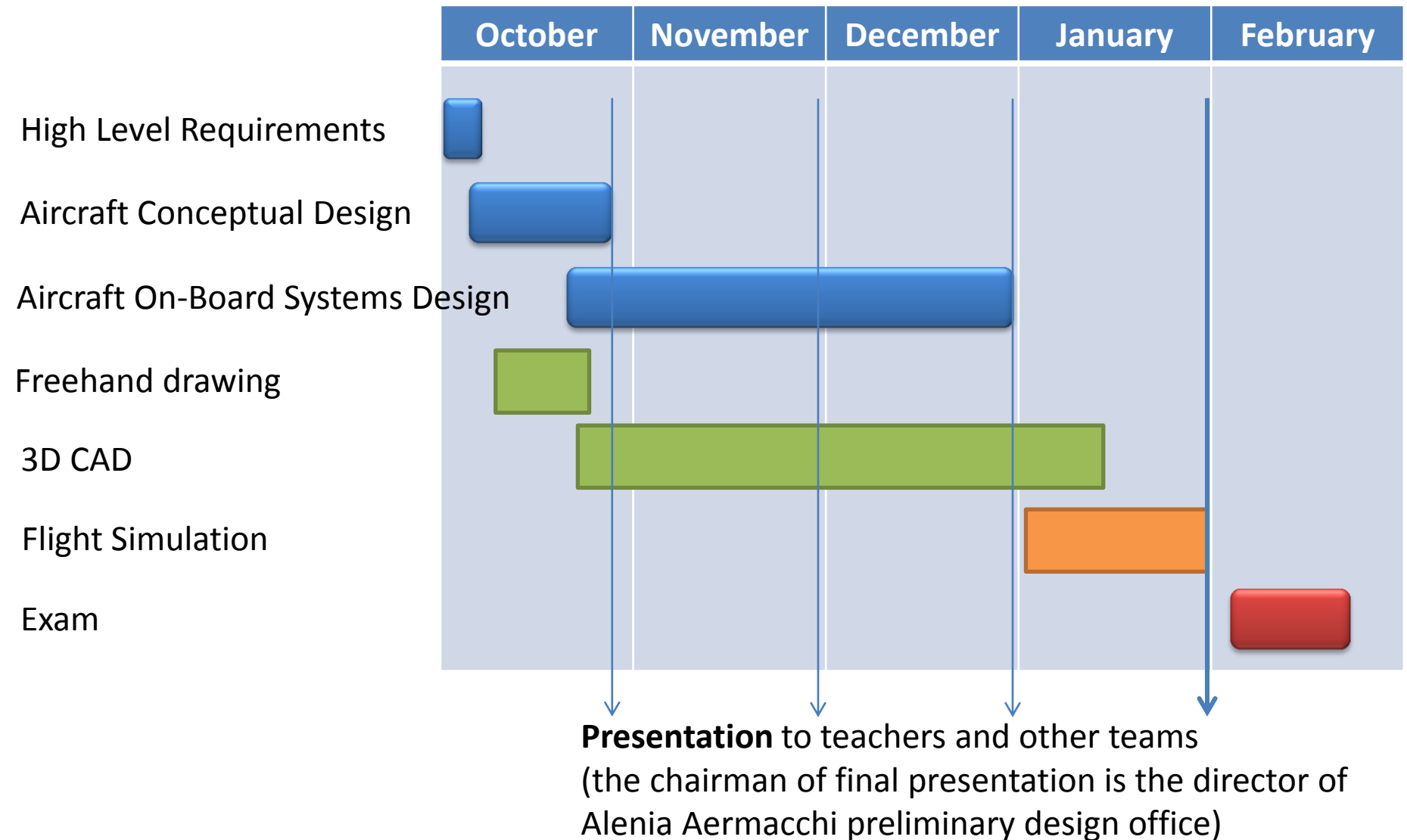
Duration: 6 months (8 ECTS)

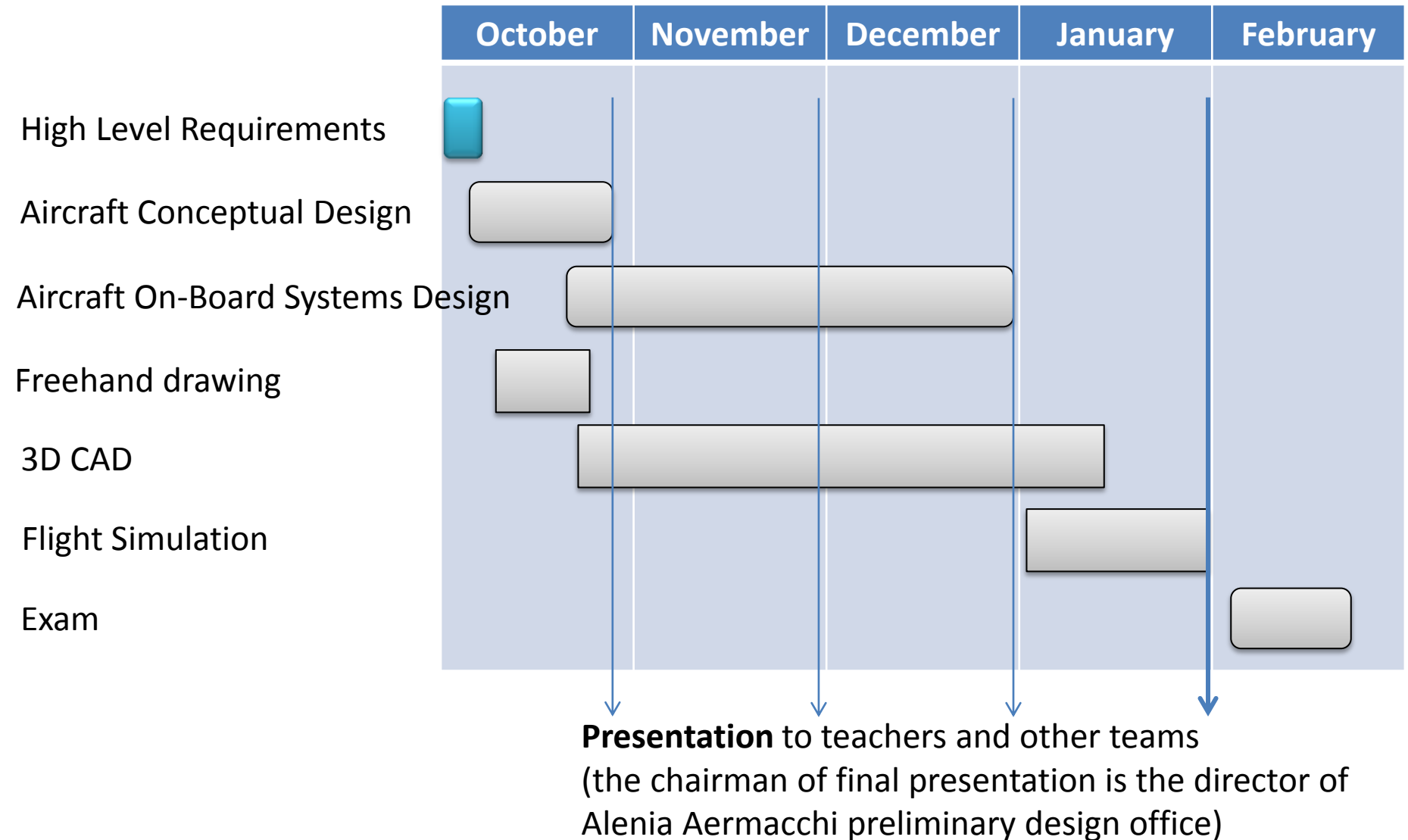
Aim of the course:

- to provide students with the capability to carry out a conceptual design of a given aircraft
- to give knowledge to perform the preliminary design of the on-board systems in an integrated way
- to enhance students' teamwork experience

- ✓ The attending students are divided in 6 -8 teams
- ✓ Each team is composed by around 5 students
- ✓ Each team will design an aircraft starting from some high level requirements. The aircraft test cases are changed yearly
- ✓ The requirements are adequately detailed to easily individuate the aircraft class but students have enough freedom in design choices
- ✓ During every lesson the students' work is checked and evaluated
- ✓ Once a month students present their work to the other teams and teachers







1st Team: Conventional jet-liner with innovative on-board systems

- Number of passenger 132+4
- Single aisle 6 abreast
- Max range 5000 km
- Max speed (@ 10000 m) 880 km/h
- Field length 2000 m
- Innovative on-board systems



3rd Team: acrobatic general aviation / Screener

- Number of passenger / pilot: 1/ 1 or 0/2
- Max range 2500 km
- Max speed (@ 7000 m) 400 km/h
- Field length 900 m
- Acrobatic flight envelop
- Hybrid propulsion (piston + electric)



2nd Team: General aviation long range

- Number of passenger / pilot : 4 / 2 or 5 / 1
- Max range 3500 km
- Max speed (@ 3500 m) 350 km/h
- Field length 1000 m
- Galley, toilet
- Relative high passenger comfort (cabin luminosity, noise reduction)



4th Team: Regional turboprop advanced architecture

- Number of passengers: 90
- Max range 1500 km
- Max speed (@ 8000 m) 650 km/h
- Field length 1000 m
- Laminar wing and fuselage



5th Team: Light jet-trainer

- Number of pilot: 2
- Tandem configuration
- Max range 1100 km
- Max speed (@ 7000 m) 750 km/h
- Field length 500 m
- Rate of climb (s.l.) 22 m/s
- Load factor: +7 / -3
- Low weight, low dimensions, low fuel consumption and operating cost



7th Team: BeePlane

- Number of passenger: 220
- Max range 5000 km
- Max speed (@ 10000 m) 880 km/h
- Field length 1700 m
- Detachable fuselage

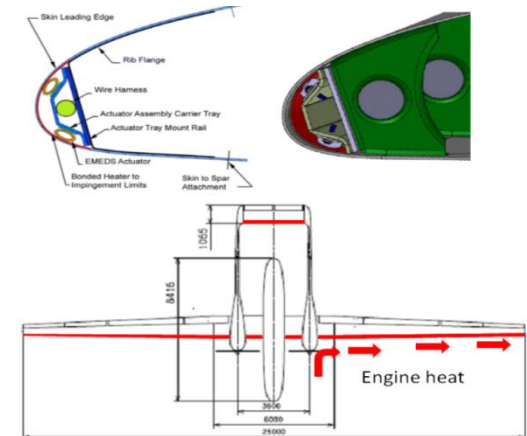
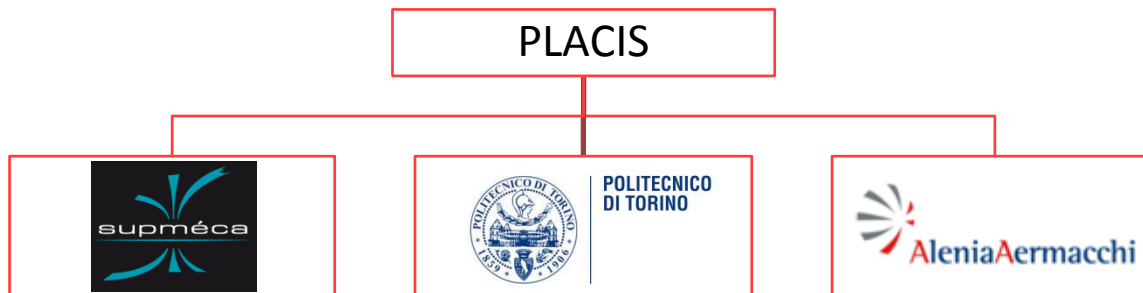
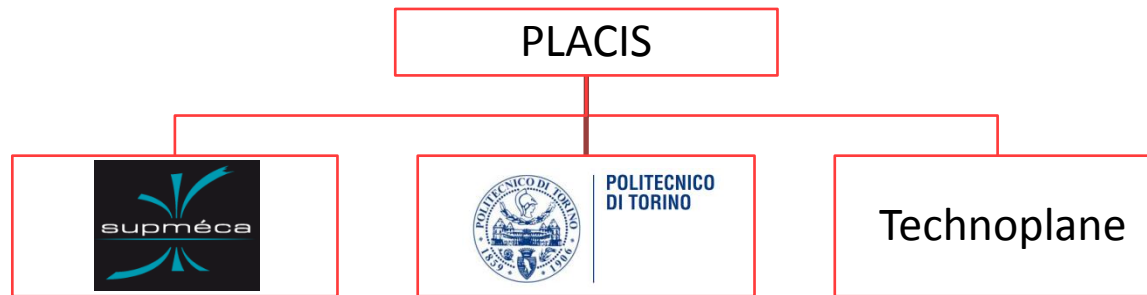


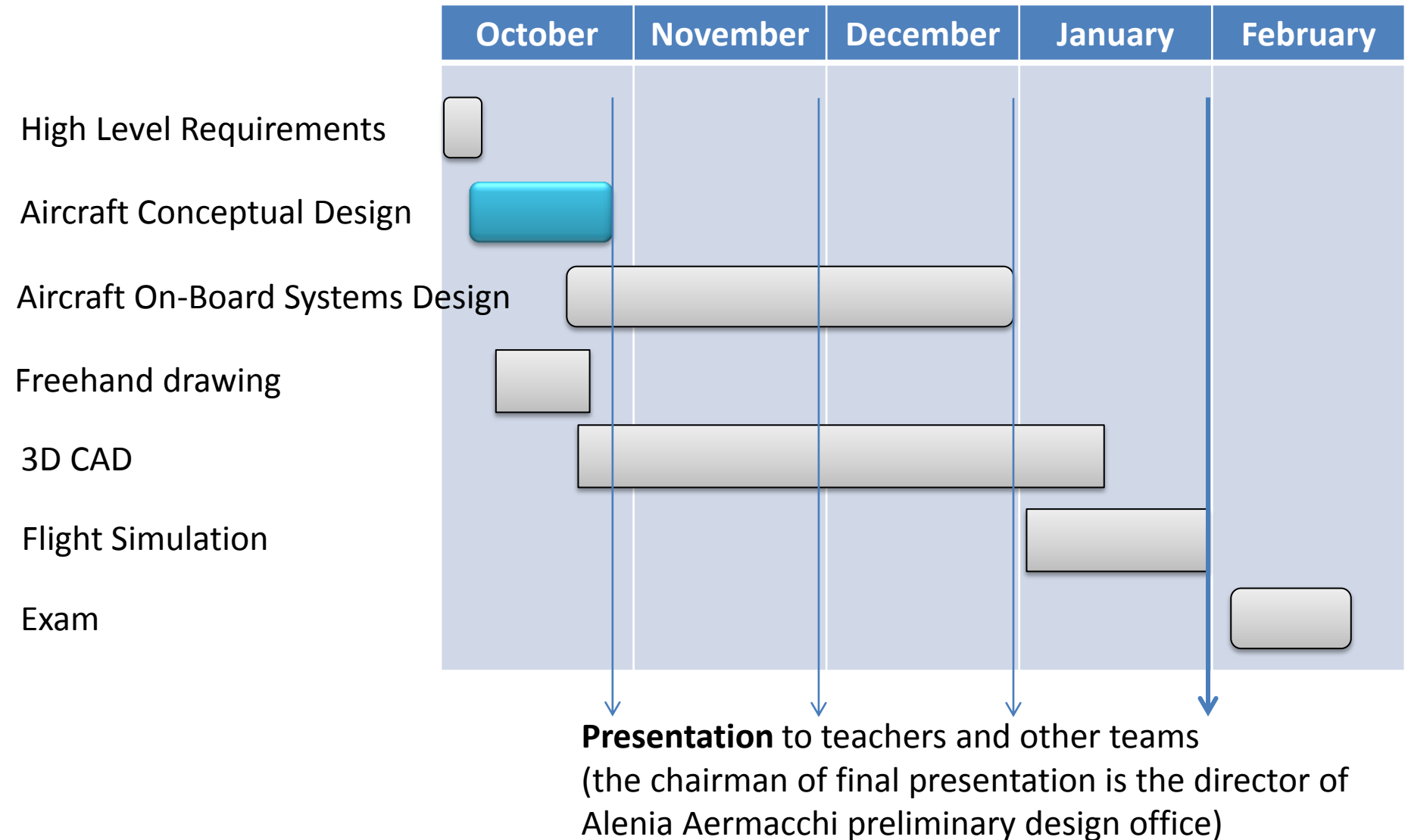
6th Team: MALE UAV civil missions

- Payload weight: 650 kg
- Max endurance: 33 hours @ 14000 m
- Field length 1600 m
- Advanced on-board system architecture (more or all-electric)



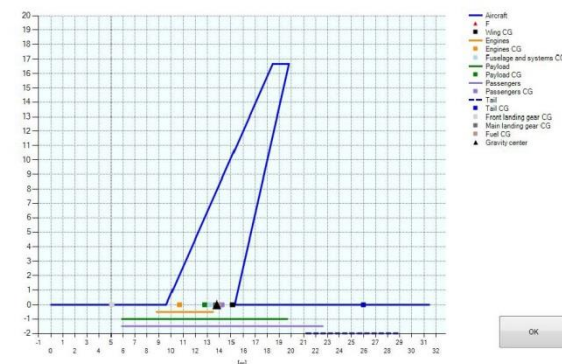
Collaboration with university Supméca (Paris) and other industries (in 2014, Alenia Aermacchi and Technoplane)





Output from aircraft
conceptual design module

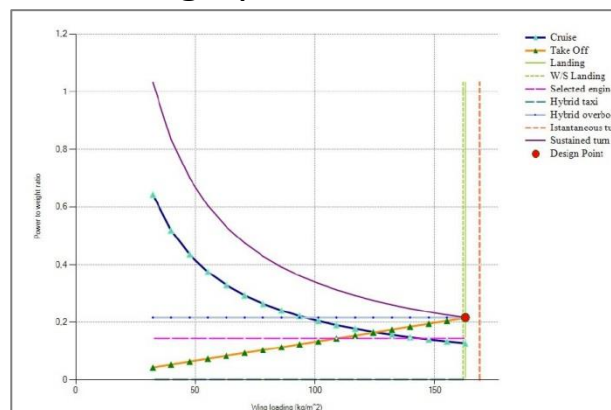
Weight and balance



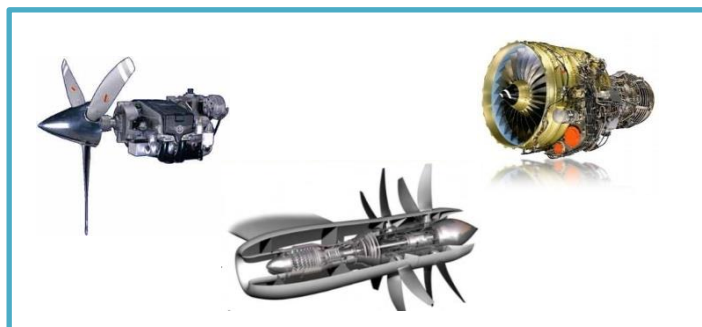
Aircraft geometry
and aerodynamic
coefficients

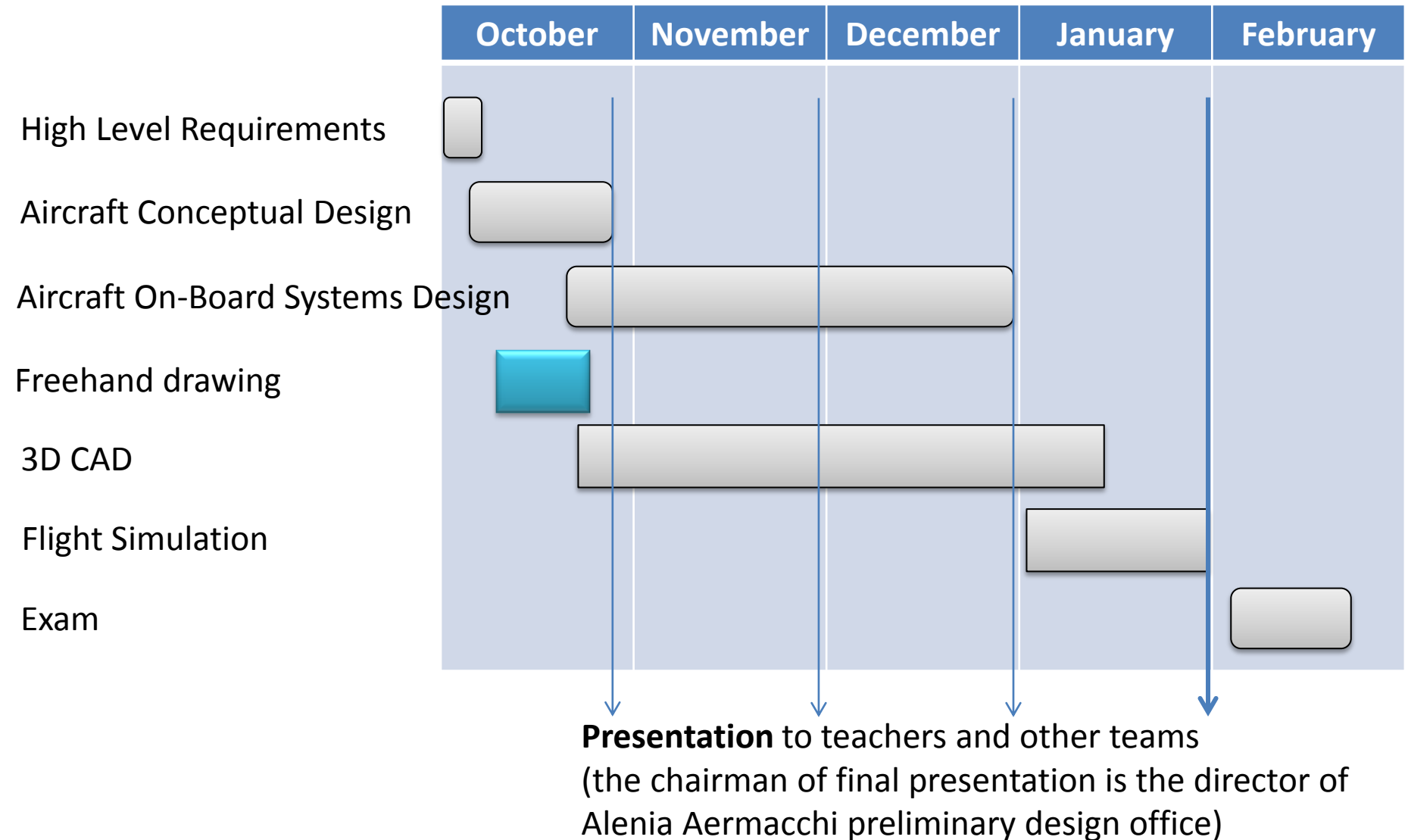


Design point

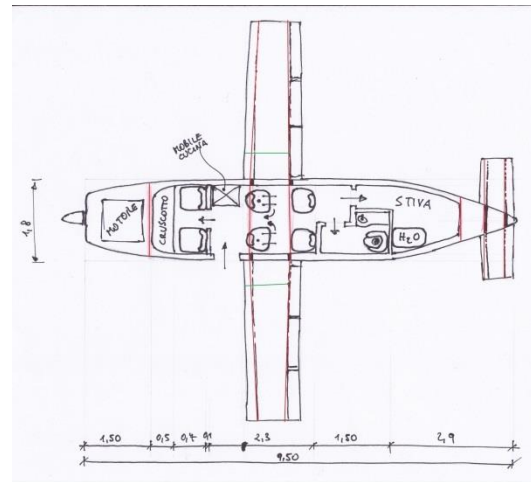
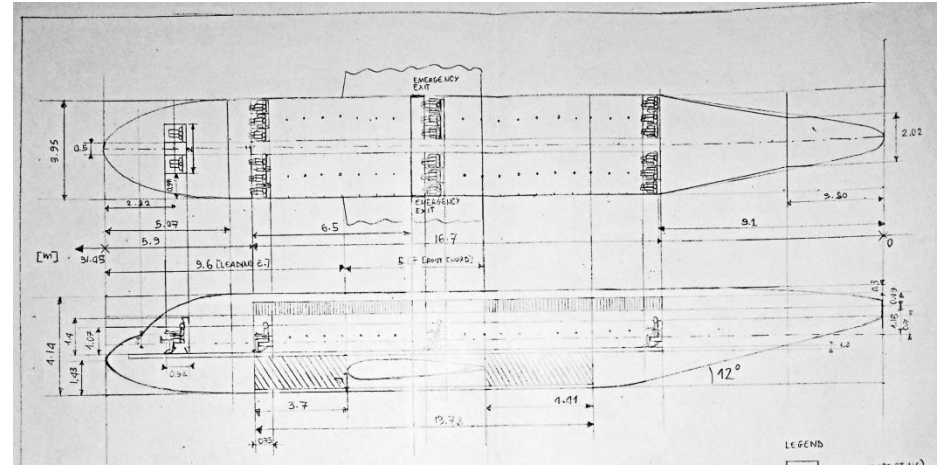
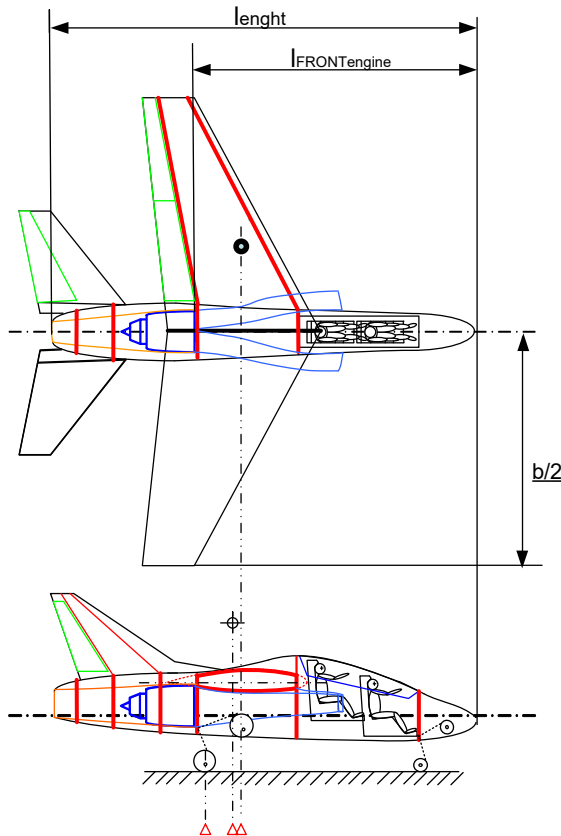


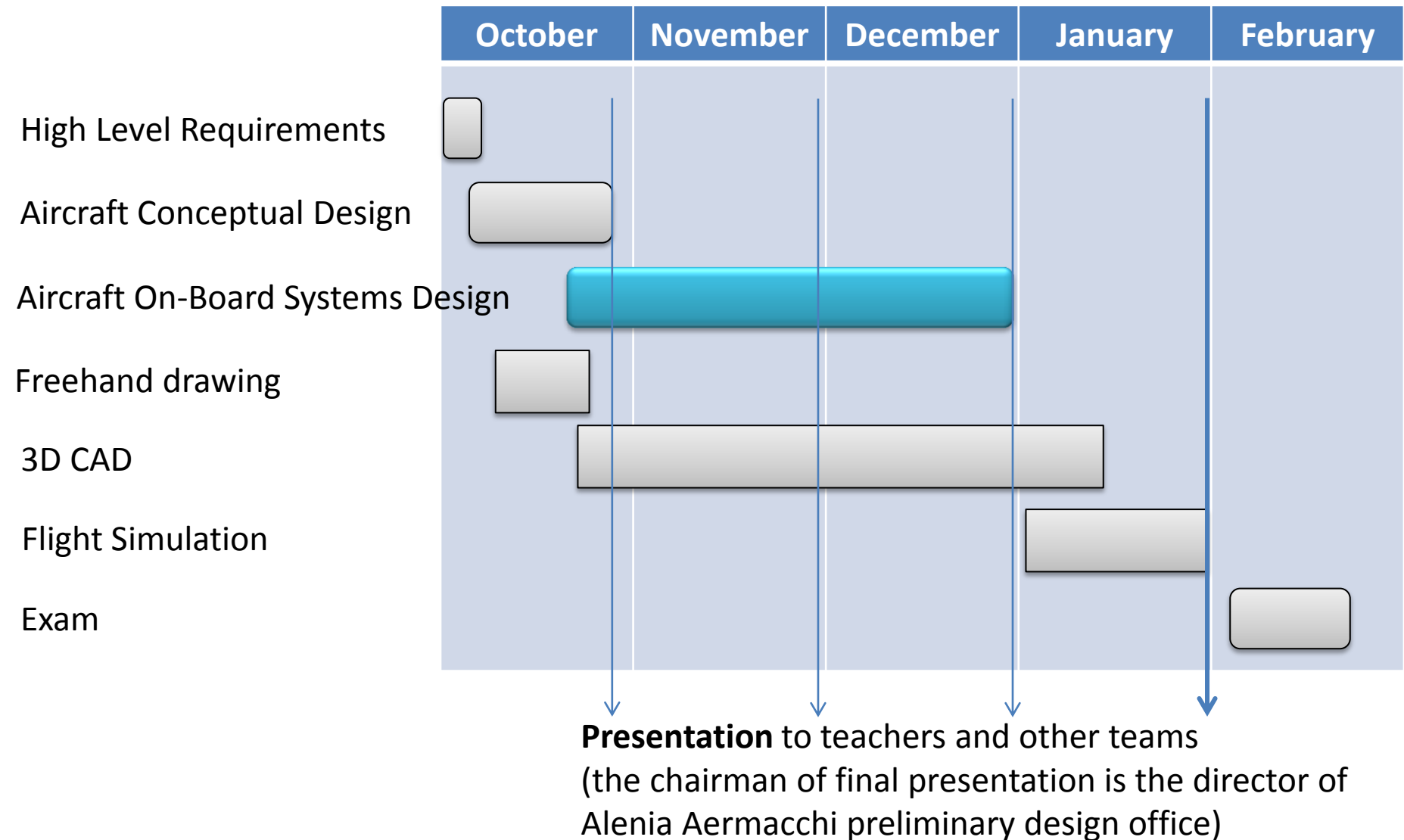
Engine
selection



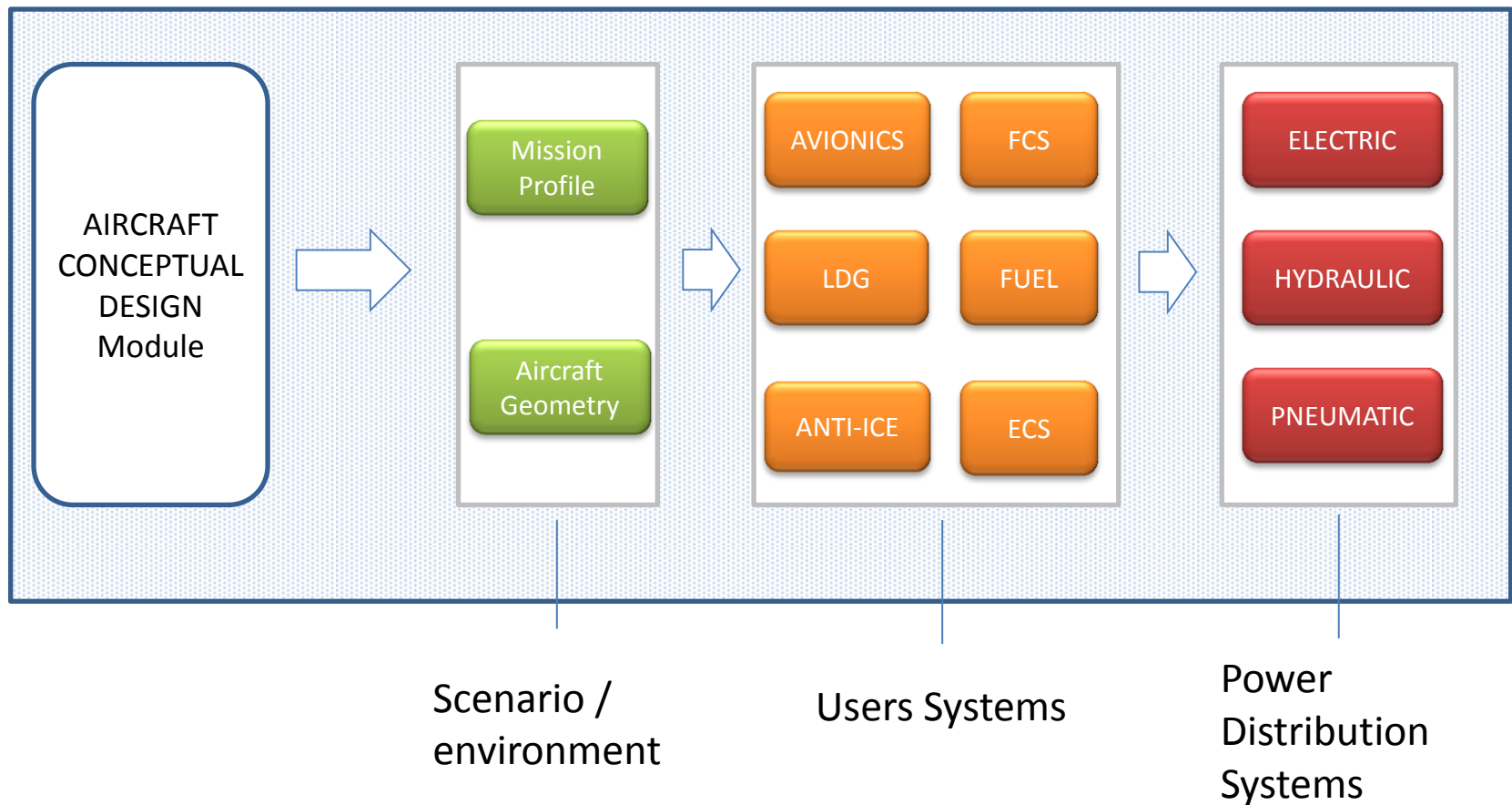


- Aircraft configuration
- Main dimensions
- Position of main elements (payload, engines, main structural elements, etc..)



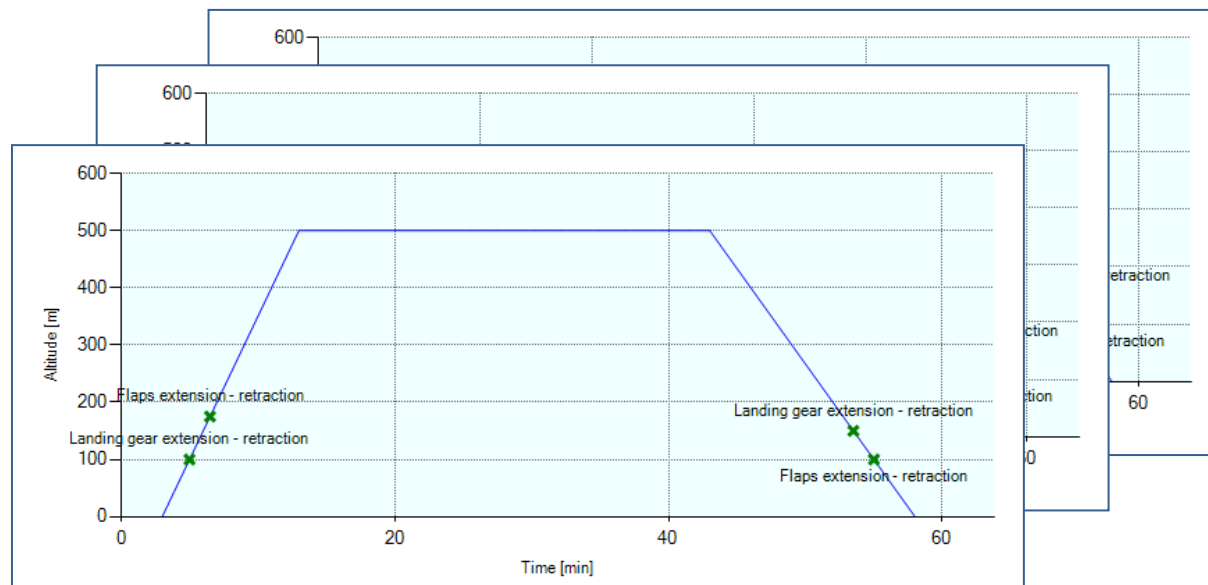


ASTRID software ----- Internal Modules

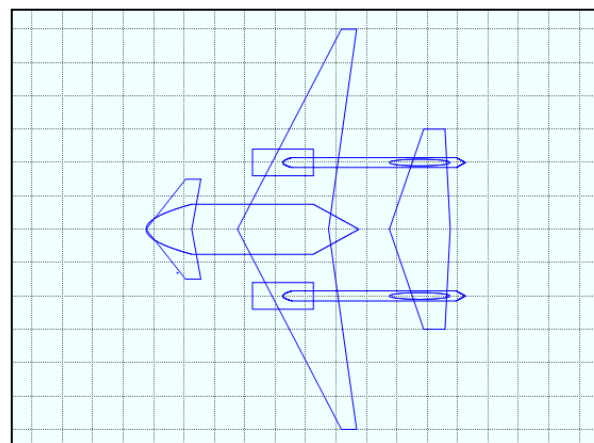


ASTRID global input

Aircraft **mission profiles** designed to take into account the on-board systems utilization



Aircraft geometry. Needed for subsystems design (e.g. distance between fuel tanks and engines etc.)



Selection of avionic equipment starting from functional analysis

Avionic system

Select an avionic subsystem:

- Navigation
- Right Control
- Displays and Controls**
- Attack
- Altro sottosistema 1
- Altro sottosistema 2

Avionic subsystem: Displays and Controls

Device	Number of devices	Number of redundancies
Electronic Flight Instrument System (EFIS)	1	0
Head Up Display (HUD)	1	0
Multi Function Display (MFD)	1	0

Number of devices: + -

Buttons: DEFINE AVIONIC SUBSYSTEM, ADD AVIONIC DEVICES, DEFINE AVIONIC DEVICES

Equipment utilization within mission profile phases

Power Budget

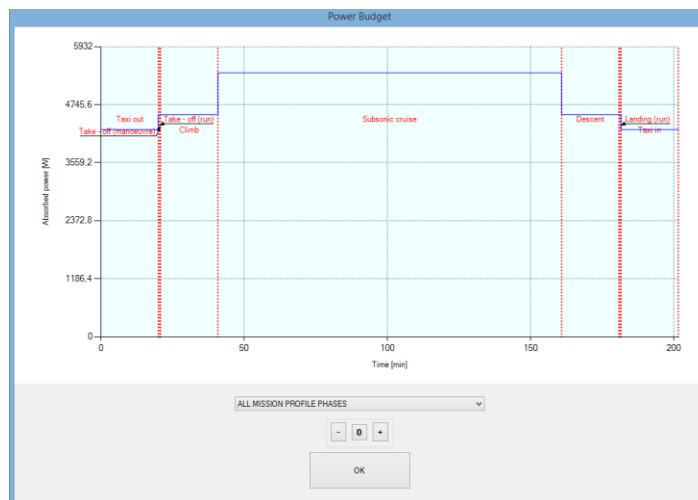
Phase: Climb

Device	Active	Electric voltage	Absorbed power [W]
Air Data System (ADS) - 1	YES	115 V AC (400 Hz)	4
Air Data System (ADS) - 2	YES	115 V AC (400 Hz)	4
Air Speed Indicator (ASI) - 1	YES	28 V DC	1
Attitude and Heading Reference System (AHRS) - 1	YES	115 V AC (400 Hz)	30
Attitude and Heading Reference System (AHRS) - 2	YES	115 V AC (400 Hz)	30
Altitude Indicator - 1	YES	28 V DC	1
Audio Control Unit (ACU) - 1	YES	28 V DC	15
Audio Control Unit (ACU) - 2	YES	28 V DC	15
Automatic Direction Finder (ADF) - 1	YES	115 V AC (400 Hz)	20
Automatic Direction Finder (ADF) - 2	YES	115 V AC (400 Hz)	20
Automatic Flight Control System (AFCS) - 1	YES	115 V AC (400 Hz)	70

Buttons: LOAD DIAGRAM, OK

Summary: Number of active devices: 62, Required power [W]: 4538

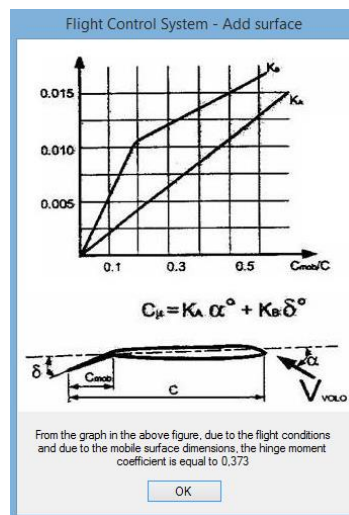
Power budget



Users (flight control surfaces) definition

Surface name	Area [in²]	Area [ft²]	Mean chord [in]	Mean chord [ft]	Mobile surface chord [in]
Left aileron	1.95	20.39	1.9	6.23	0.64
Right aileron	1.95	20.39	1.9	6.23	0.64
Left elevator	4.3	46.285	2.28	7.48	0.74
Right elevator	4.3	46.285	2.28	7.48	0.74
Fludder	8	86.111	3.79	12.43	1.24
Left speedbrake 1	1.05	11.302	-	-	0.64
Right speedbrake 1	1.05	11.302	-	-	0.64
Left speedbrake 2	1.05	11.302	-	-	0.64
Right speedbrake 2	1.05	11.302	-	-	0.64
Left speedbrake 3	1.05	11.302	-	-	0.64
Right speedbrake 3	1.05	11.302	-	-	0.64
Left speedbrake 4	1.05	11.302	-	-	0.64
Right speedbrake 4	1.05	11.302	-	-	0.64
Left speedbrake int	1.05	11.302	-	-	0.55
Right speedbrake int	1.05	11.302	-	-	0.55

Estimation of the key design factors



Selection of technology (electrical, hydraulic...)

Actuator power supply: Hydraulic

Electric voltage: 28 V DC, 270 V DC, 230 V AC wild freq, 115 V AC const freq (400Hz), 115 V AC wild freq, other

Hydraulic alternation nominal pressure: 205.9955 bar, 20689655.1724 Pa, 3000 psi

Actuators: Num actuators: 2, Num redundancies: 0

1' type: ☐ Rotative motion with adaptor

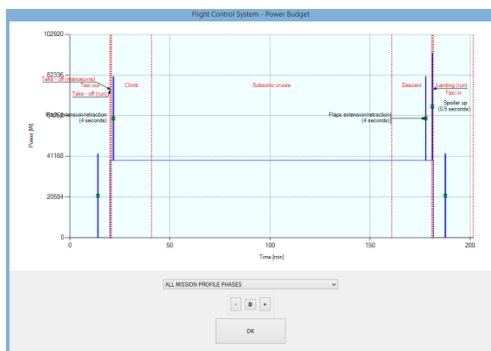
2' type: ☐ Linear motion (screw drive system)
 ☐ drive unit
 ☐ motor-actuator (1:1)

3' type: ☒ Cylinder (braz)

Presence of mobile surfaces with the same sizing: ☐

Power required and dimensions estimation

System power budget



Utilization within the mission profile phases

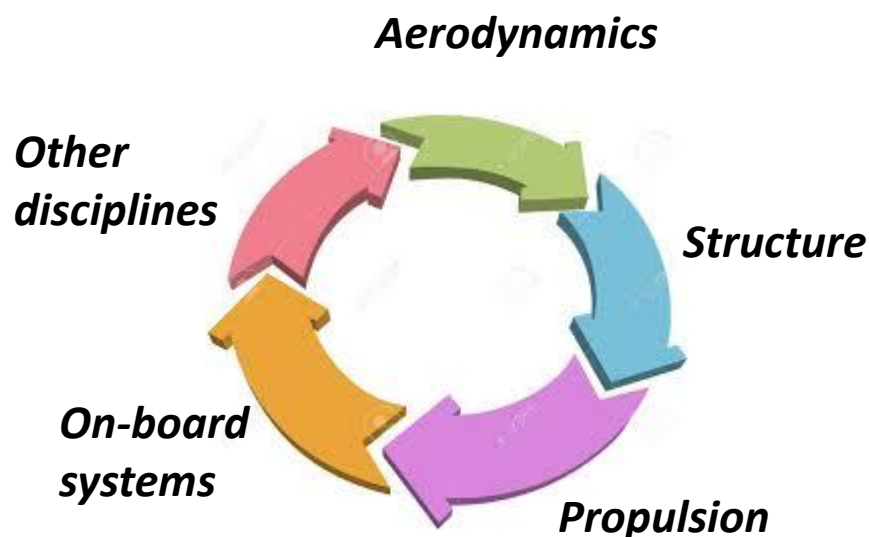
Surface	Active	Category	Power [W]
Left aileron	YES	Hydraulic	2.313.16
Right aileron	YES	Hydraulic	8.189.31
Left elevator	NO	-	-
Right elevator	NO	-	-
Fludder	NO	-	-
Left speedbrake 1	NO	-	-
Right speedbrake 1	NO	-	-
Left speedbrake 2	NO	-	-
Right speedbrake 2	NO	-	-
Left speedbrake 3	NO	-	-
Right speedbrake 3	NO	-	-
Left speedbrake 4	NO	-	-
Right speedbrake 4	NO	-	-

Surface	Category	Total weight [kg]	Required power by the mobile surface actuation [W]
Left aileron	Hydraulic	10.94	2.313.16
Right aileron	Hydraulic	10.94	2.313.16
Left elevator	Hydraulic	13.14	8.189.31
Right elevator	Hydraulic	13.14	8.189.31
Fludder	Hydraulic	19.35	18.141.57
Left speedbrake 1	Hydraulic	4.26	2.264.68
Right speedbrake 1	Hydraulic	4.26	2.264.68
Left speedbrake 2	Hydraulic	5.07	8.206.23
Right speedbrake 2	Hydraulic	5.07	8.206.23
Left speedbrake 3	Hydraulic	5.1	8.206.23
Right speedbrake 3	Hydraulic	5.1	8.206.23
Left speedbrake 4	Hydraulic	5.03	6.347.04
Right speedbrake 4	Hydraulic	5.03	6.347.04

Total actuation system weight [kg]: 250.33

After this design step, students' team should redesign the aircraft

Be familiar with the impact of each discipline on the other should be a primary task within Aircraft MDO optimization

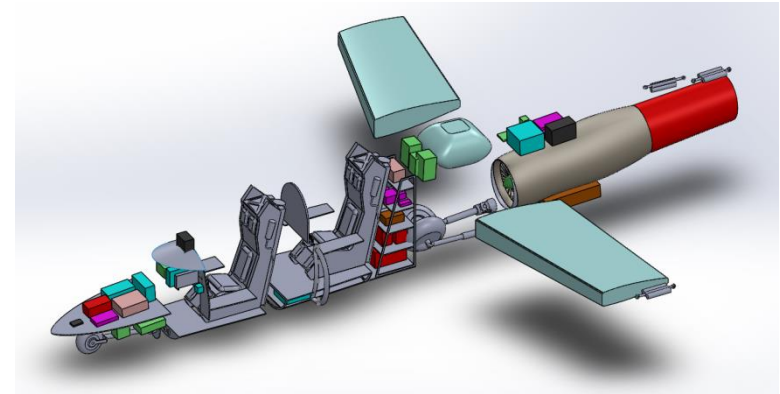
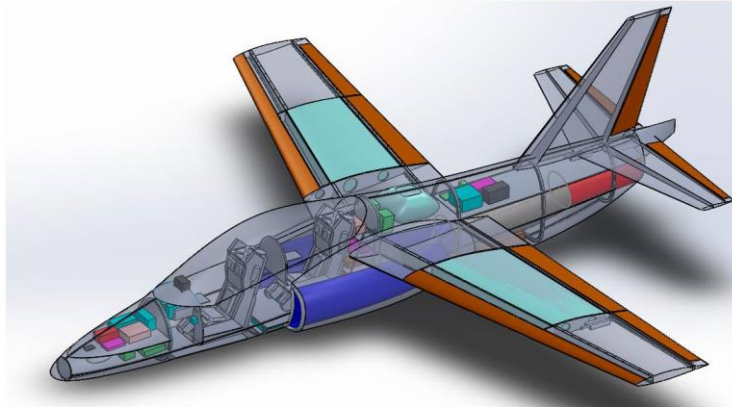


Aircraft On-board systems represent:

- 15% (liner) ÷ 30% (fighter) of aircraft empty weight
- 30% ÷ 50% of aircraft cost

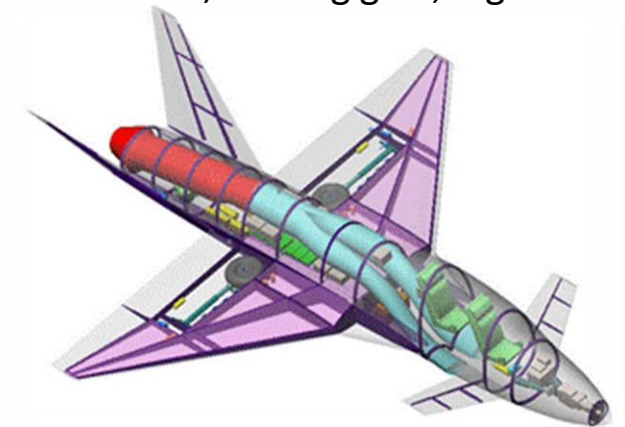
ATA 21	AIR CONDITIONING AND PRESSURIZATION
ATA 22	AUTO FLIGHT
ATA 23	COMMUNICATIONS
ATA 24	ELECTRICAL POWER
ATA 25	EQUIPMENT/FURNISHINGS
ATA 26	FIRE PROTECTION
ATA 27	FLIGHT CONTROLS
ATA 28	FUEL
ATA 29	HYDRAULIC POWER
ATA 30	ICE AND RAIN PROTECTION
ATA 31	INDICATING / RECORDING SYSTEM
ATA 32	LANDING GEAR
ATA 33	LIGHTS
ATA 34	NAVIGATION
ATA 35	OXYGEN
ATA 36	PNEUMATIC
ATA 37	VACUUM
ATA 38	WATER/WASTE
ATA 39	ELECTRICAL - ELECTRONIC PANELS AND MULTIPURPOSE COMPONENTS
ATA 40	MULTISYSTEM
ATA 41	WATER BALLAST
ATA 42	INTEGRATED MODULAR AVIONICS
ATA 44	CABIN SYSTEMS
ATA 45	DIAGNOSTIC AND MAINTENANCE SYSTEM
ATA 46	INFORMATION SYSTEMS
ATA 47	NITROGEN GENERATION SYSTEM
ATA 48	IN FLIGHT FUEL DISPENSING
ATA 49	AIRBORNE AUXILIARY POWER
ATA 50	CARGO AND ACCESSORY COMPARTMENTS

Some examples of the impact of on-board systems on the other design disciplines :



➤ On-board systems integration:

- Impact on aircraft stability (influence on aircraft C.G.)
- Position constraint and volume allocations (e.g. fuel tank for liner, landing gear, flight control actuator, radar etc.)
- Reduction of power / thrust available
- Handling qualities (moment of inertia)
- RAMS
- Cost (Development, Production and Operating)



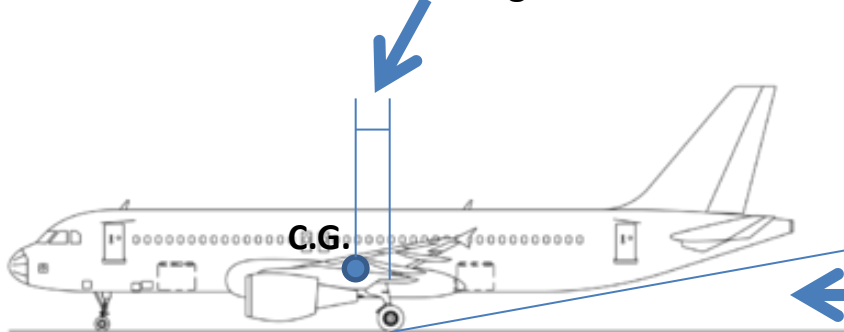
➤ Landing gear integration

- Influence on wing or fuselage geometry
- Aerodynamics (external vane)
- Take-off / landing performance
- A/C stability on ground

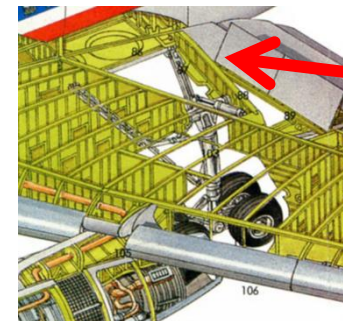


Landing gear fairing

This distance affects pitch moment during rotation

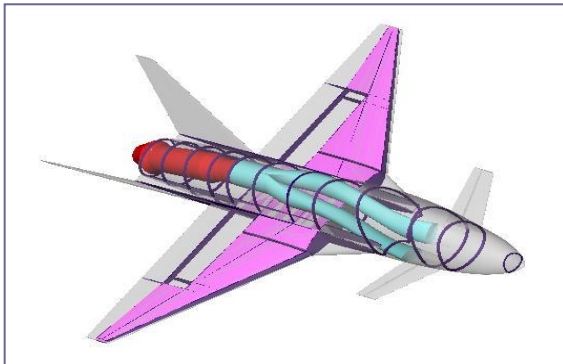


Landing gear length affects tail shape (tail clearance)

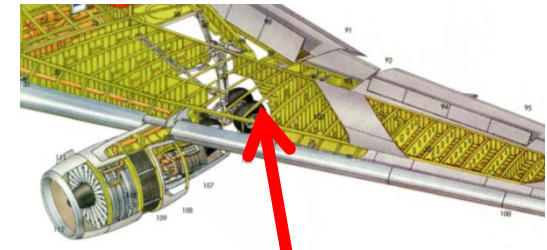


Structure arrangement

Some example of the impact of on-board system on the other design disciplines :



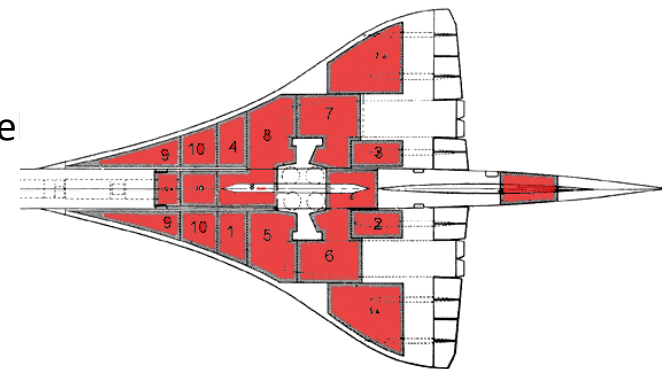
External fuel tanks



- Distance between spares
- ribs geometry

➤ Fuel system integration:

- Impact on fuselage and wing geometry
- Aircraft performance range / endurance (quantity of fuel storable)
- Aerodynamics (when external fuel tanks are needed)
- Influence on aircraft stability



Some example of the impact of on-board system on the other design disciplines :

➤ **Avionic system integration:**

- Aerodynamics (Air intakes, antennas, external POD)
- Wing / fuselage geometry
- Airframe material (radome, EM transparent material)

Fuselage enlargement needed to store satcom antenna



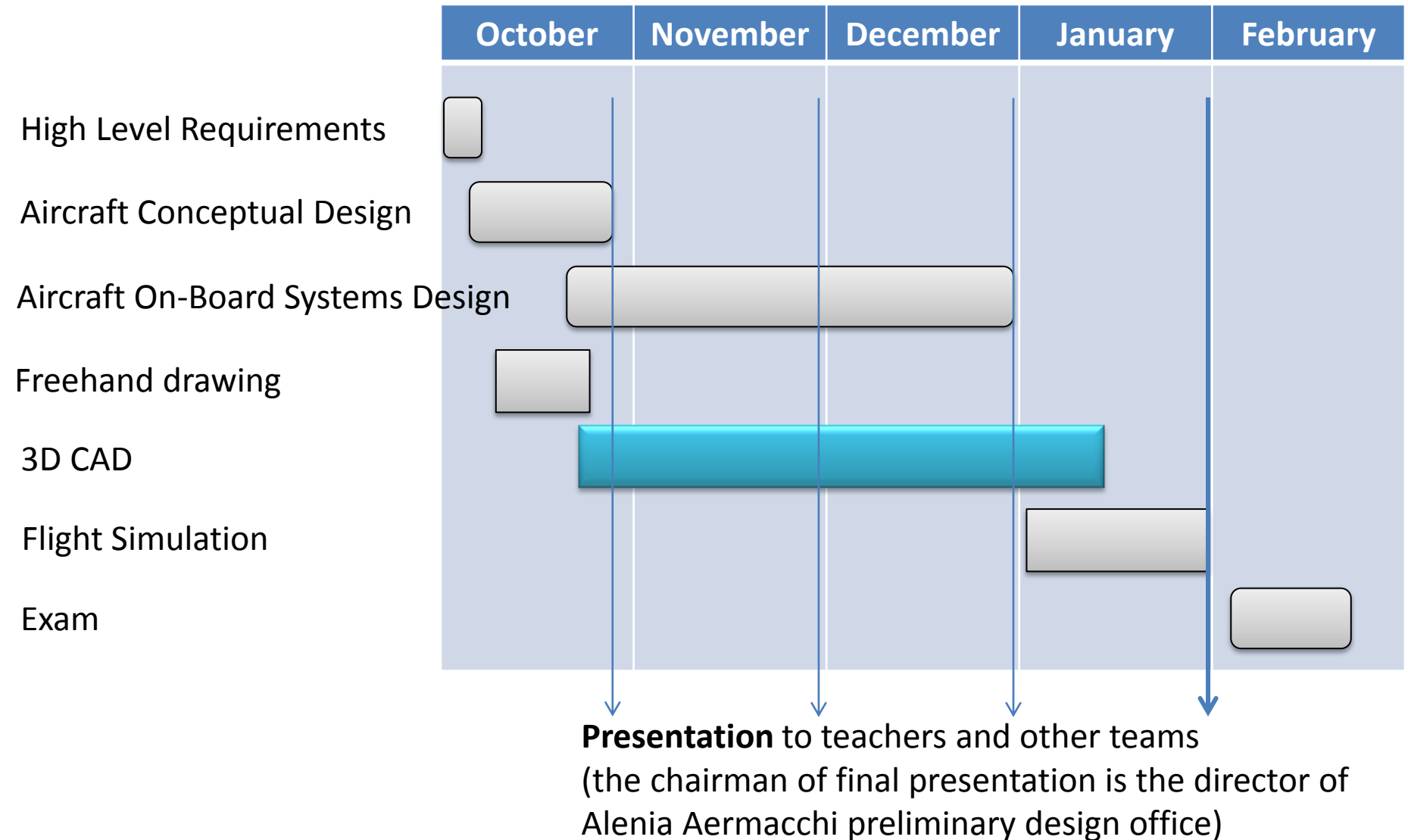
Avionics POD

➤ **Flight control system** (e.g. actuator speed, actuator dimensions, etc.)

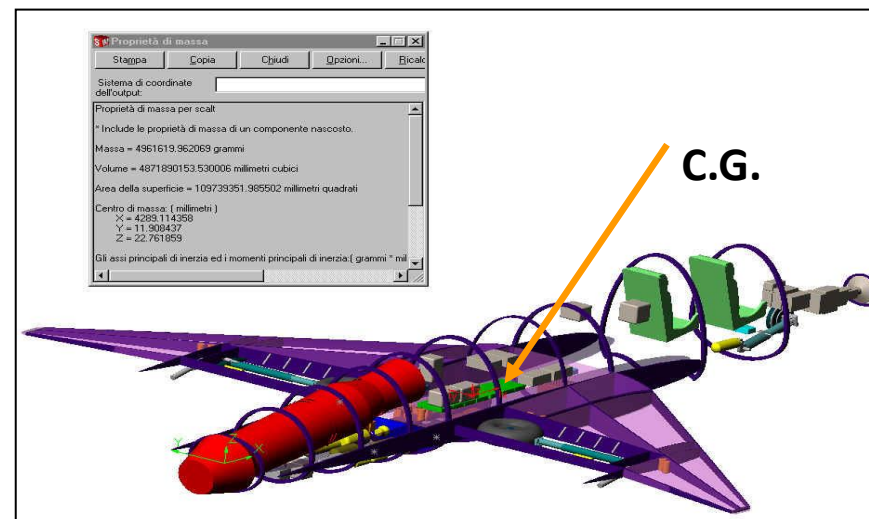
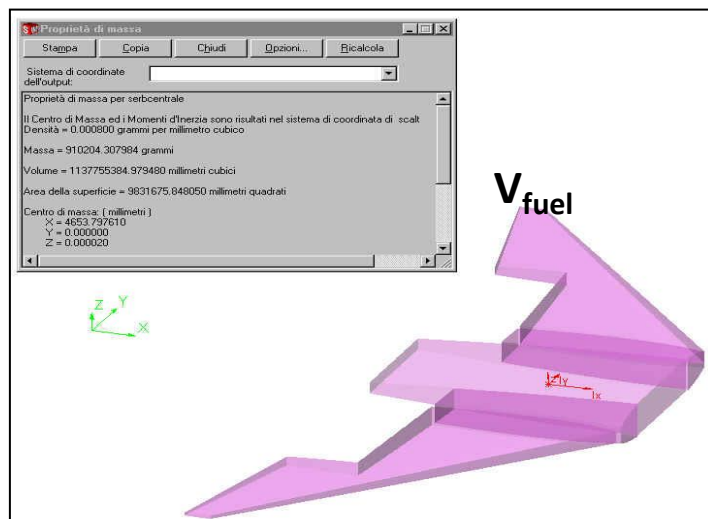
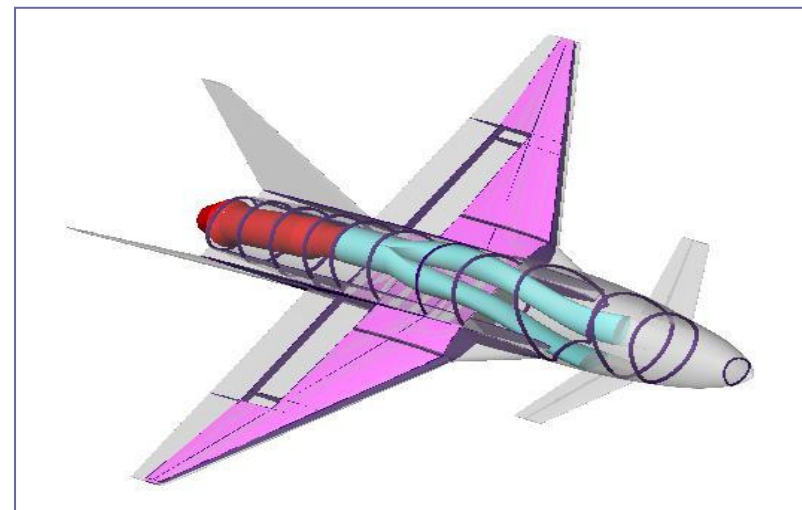
- Influence on aircraft handling qualities
- Wing aerodynamic drag

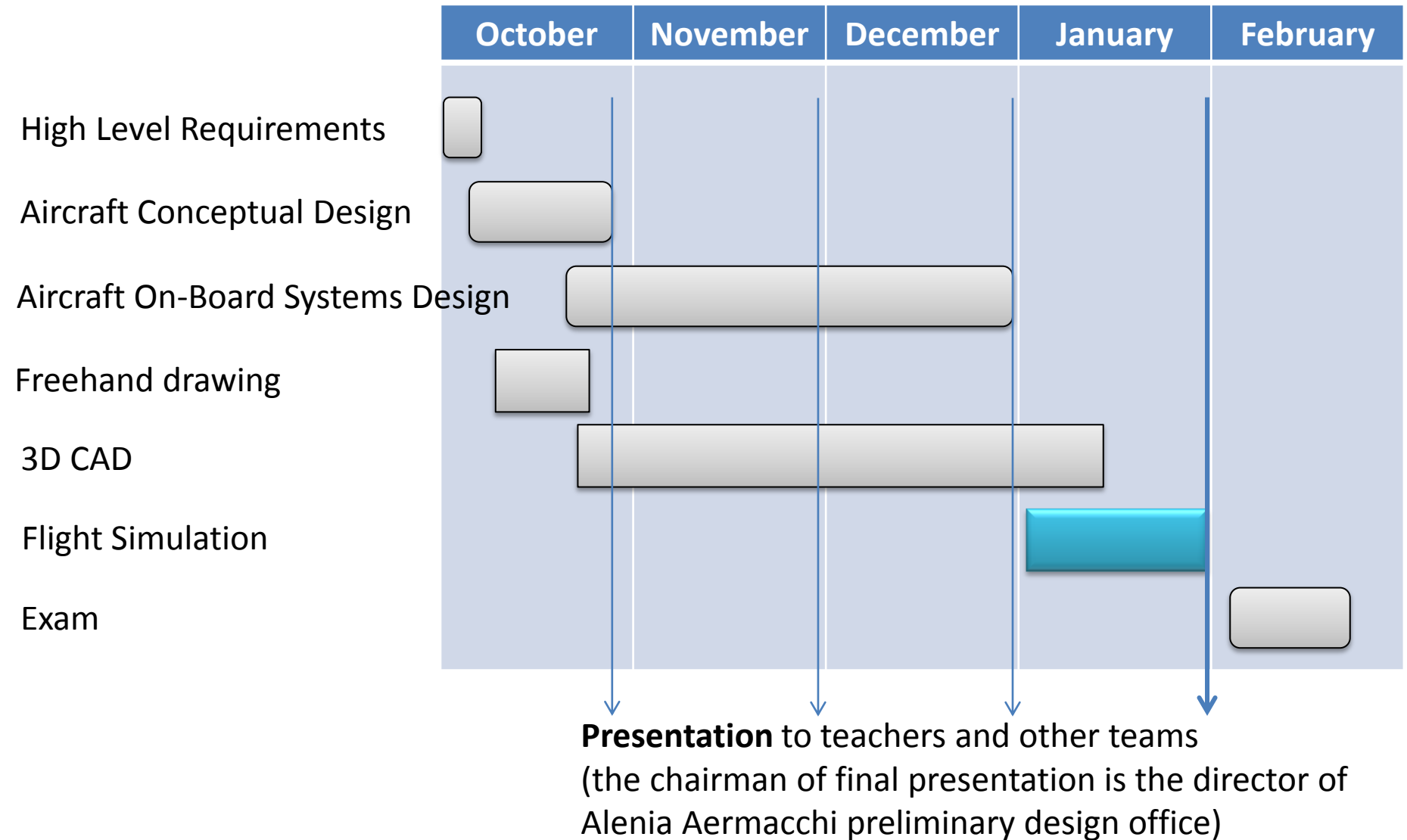
Flap fairings



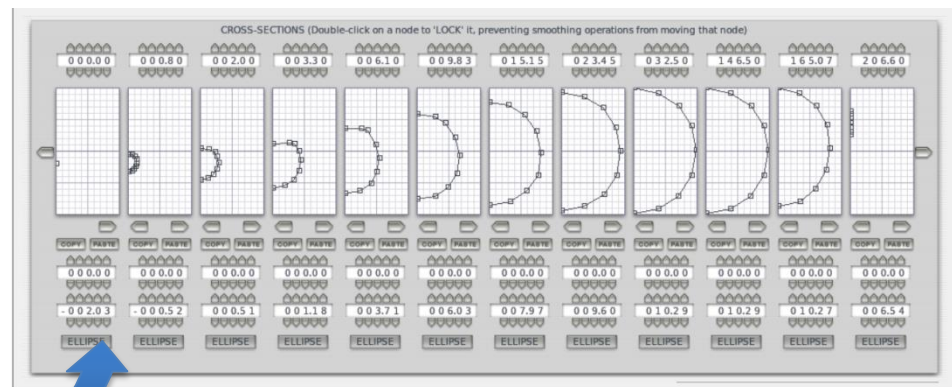
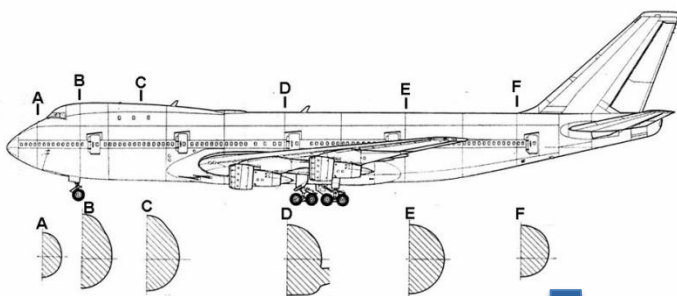


- Physical aircraft components integration
- Verification of fuel storable
- C.G. position
- Aircraft wet area

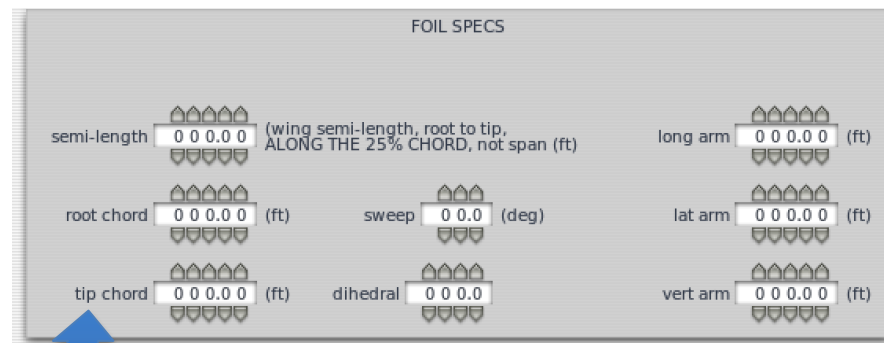
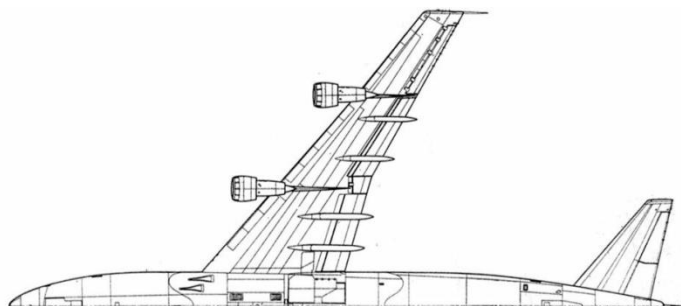




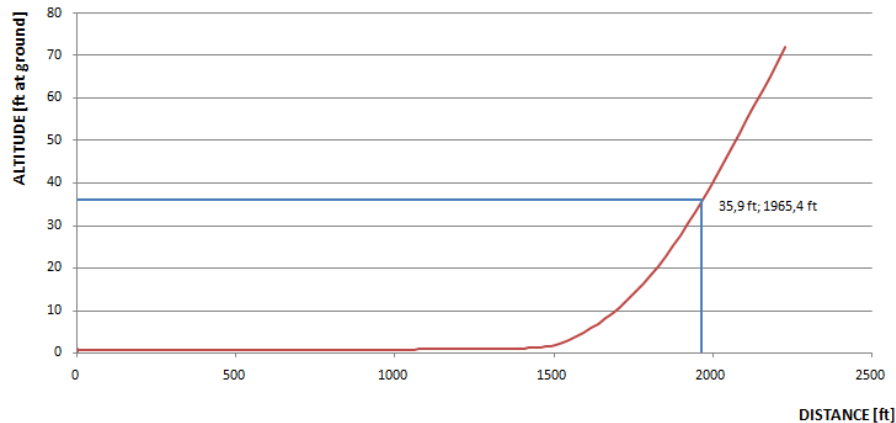
Fuselage layout



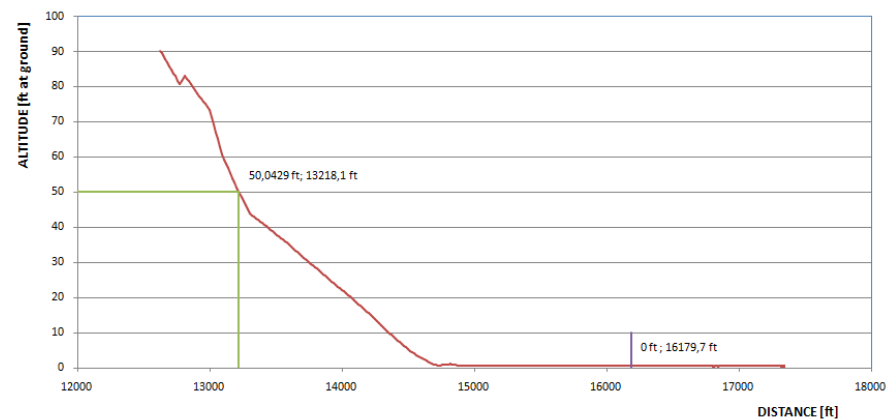
Wing layout



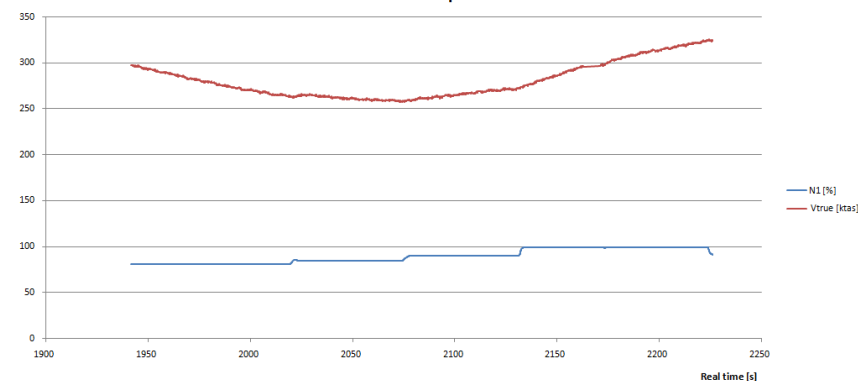
TAKE OFF RUNWAY LENGTH 1965,4 ft = 598 m

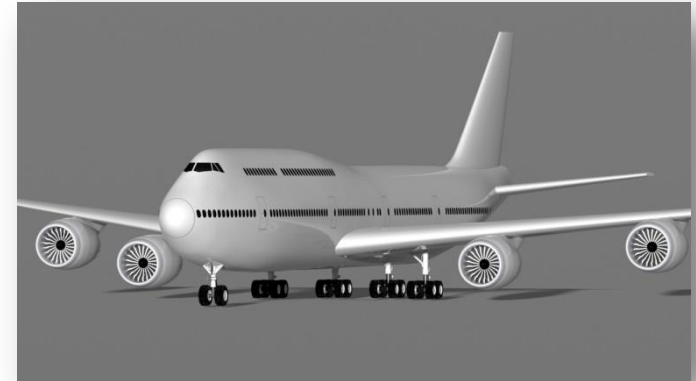


LANDING RUNWAY LENGTH: 2962 ft = 903 m

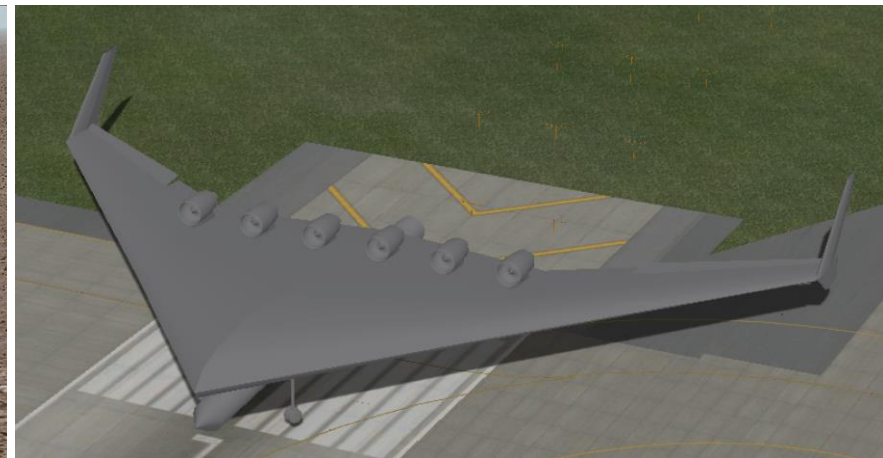
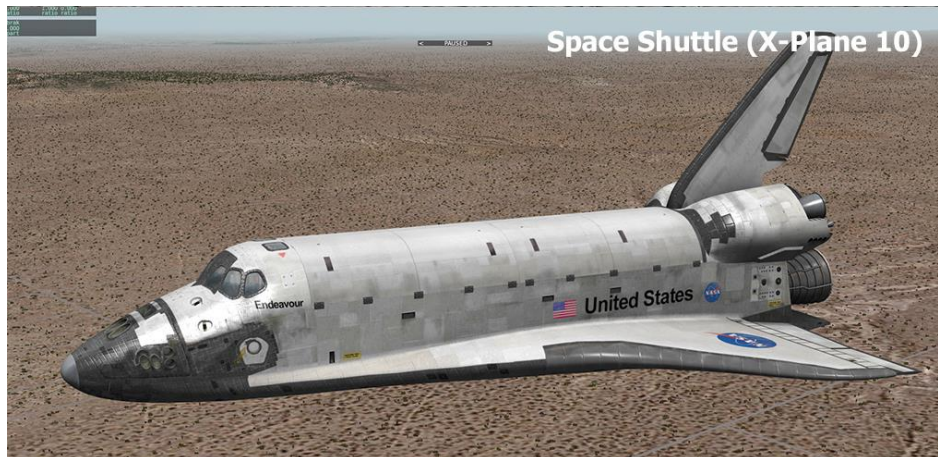


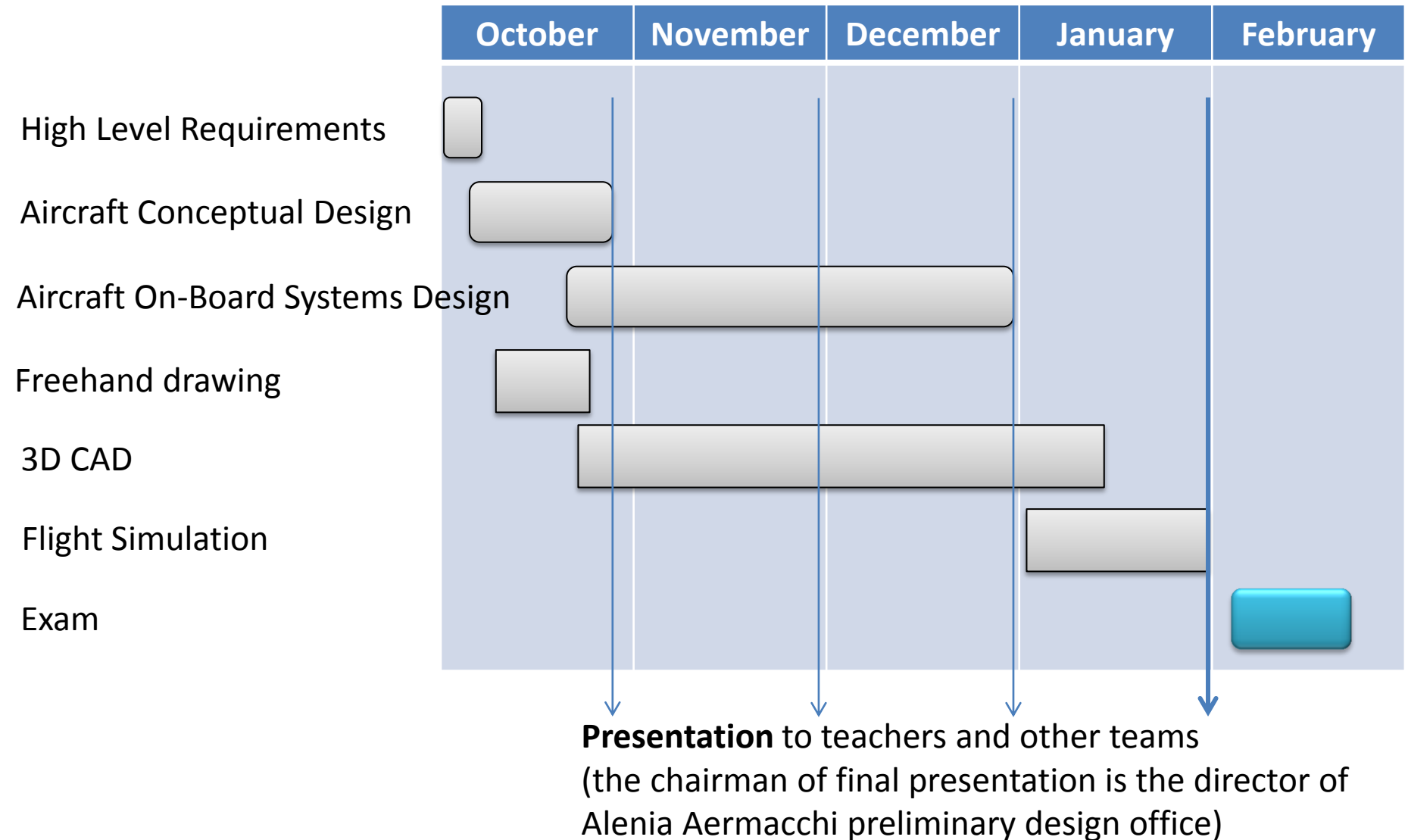
Cruise speed





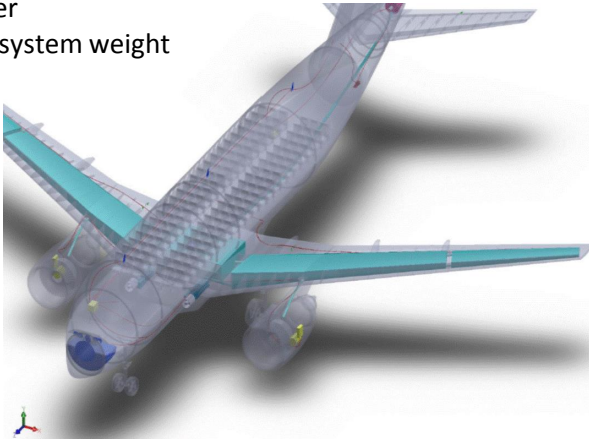
Examples of software's capabilities





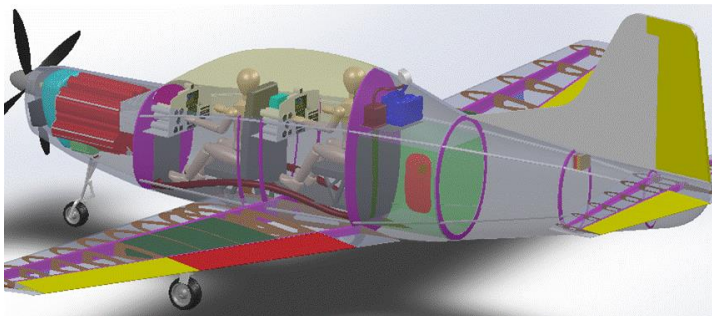
1st Team: Conventional jet-liner with innovative on-board systems

- Bleedless engine
- 270 V DC primary power
- Reduction in on-board system weight



3rd Team: acrobatic general aviation / Screener

- Hybrid propulsion
- 270 V DC electric system, electric motor and batteries for propulsion



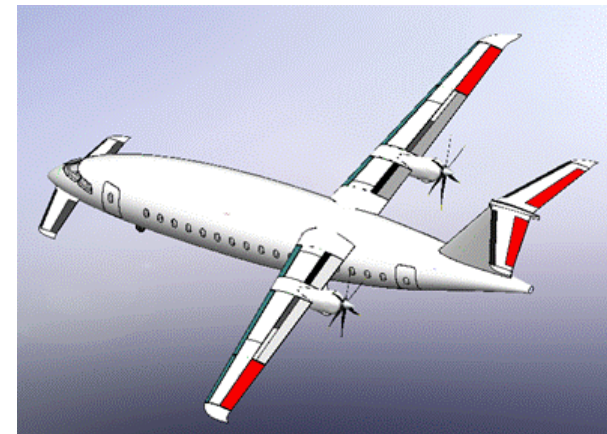
2nd Team: General aviation long range

- Diesel engine to improve fuel efficiency
- Electric de-icing
- High voltage electric system



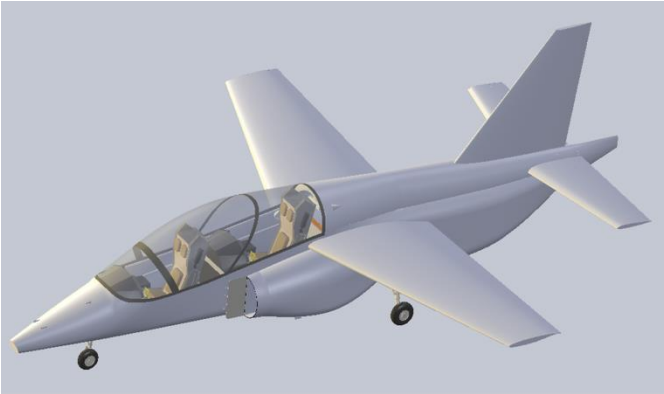
4th Team: Regional turboprop advanced architecture

- All-electric on-board system
- Uneven passenger's seats disposition



5th Team: Light jet-trainer

- Difficulty of comply with takeoff requirement
- Engine selection, fuel efficiency limited by engine installation and available volume



6th Team: MALE UAV civil missions

- Diesel engines to obtain endurance required
- New (TMEDS) de-icing system to reduce electric consumption



7th Team: BeePlane

- Difficulty of achieving required cruise speed and altitude

