Creation of Requirements and Set of Mission Specifications, Design and Operational Effectiveness of Aviation Systems: Main Tasks, Approaches, Education

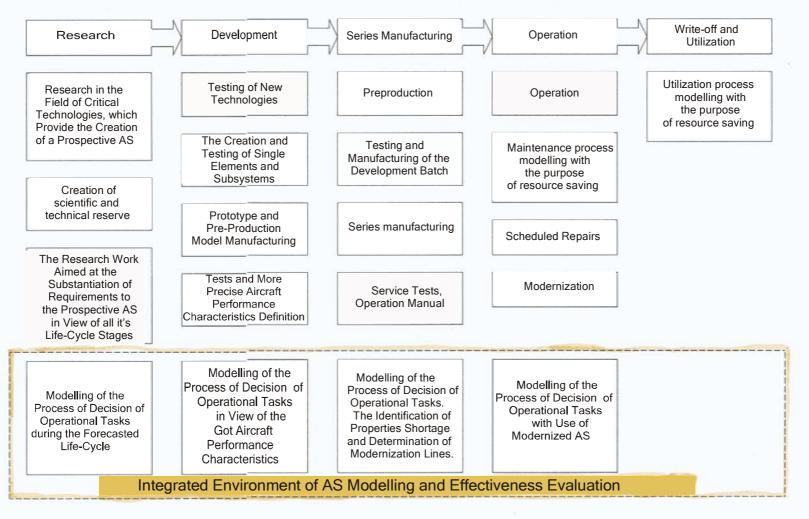
Vladimir N. Zhuravlev

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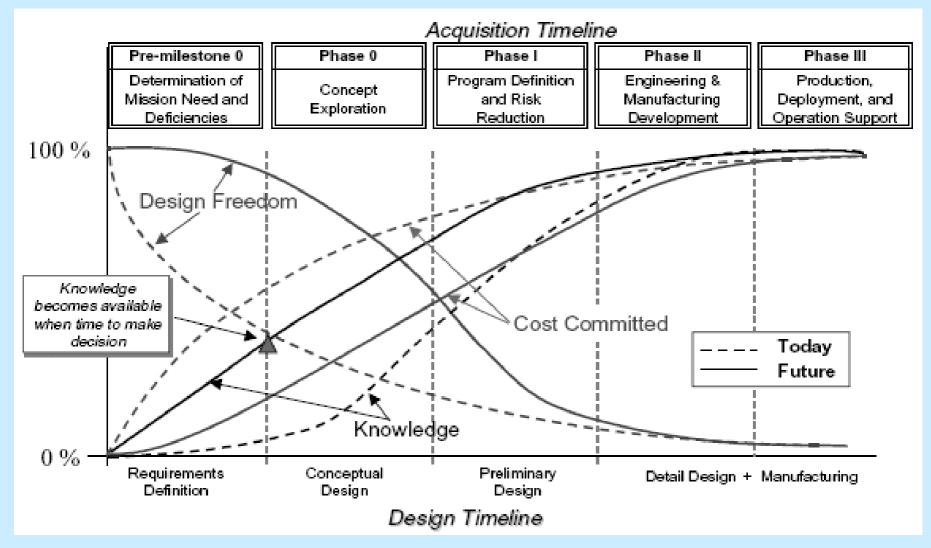
> EWADE 2007 SSAU, Samara, Russia

Modelling during aircraft life-cycle





The Relationship of Design Freedom, Knowledge & Cost Committed



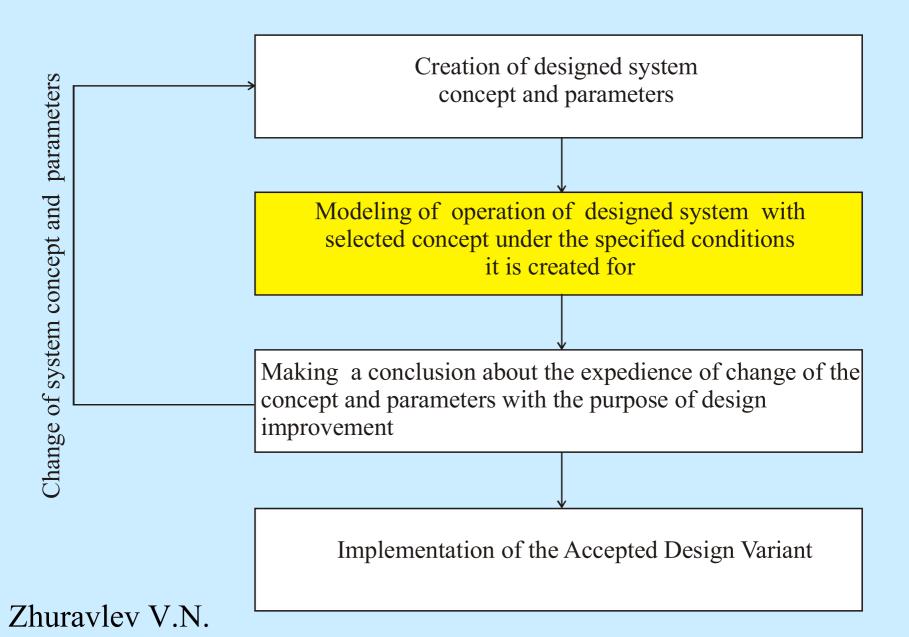
Definition of Complex Aviation System

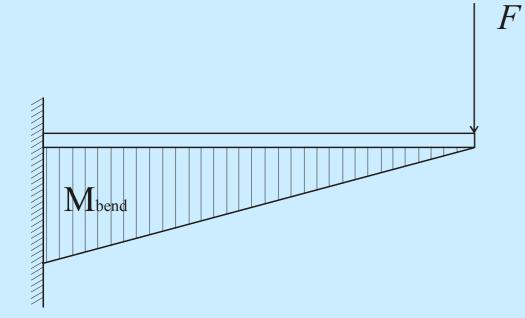
Complex Aviation System (CAS) consists of:

- vehicle
 - airframe,
 - propulsion system,
 - main aircraft subsystems;
- onboard subsystems for specific mission task

The significance of effectiveness theory in the process of complex aircraft systems design

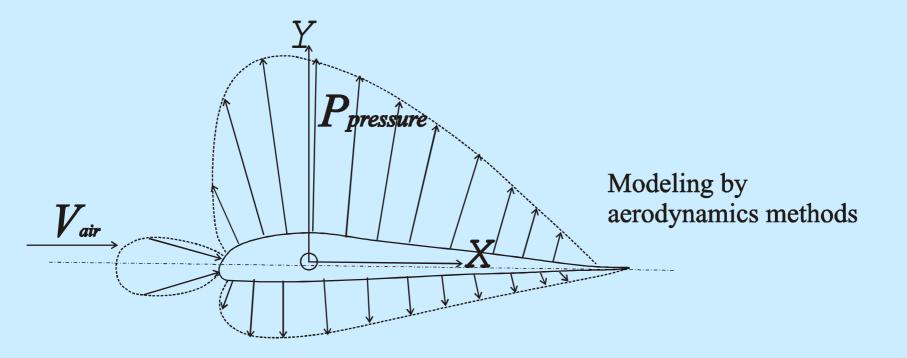
Design algorithm



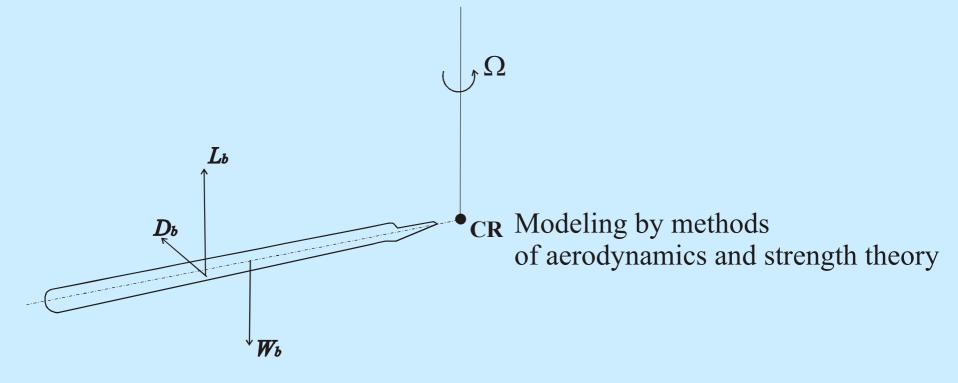


Modeling by methods of strength of materials

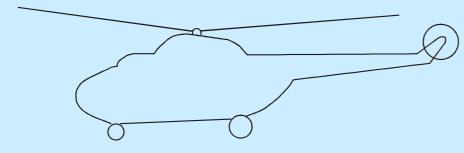
Cantilever beam



Airfoil of the rotor blade



Main Rotor blade

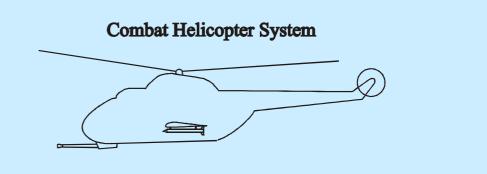


Zhuravlev V.N.

Modeling by methods of flight dynamics, aerodynamics, weight calculation, layout design, theory of powerplant characteristics calculation, economics of manufacturing and operation

Helicopter as a transport vehicle

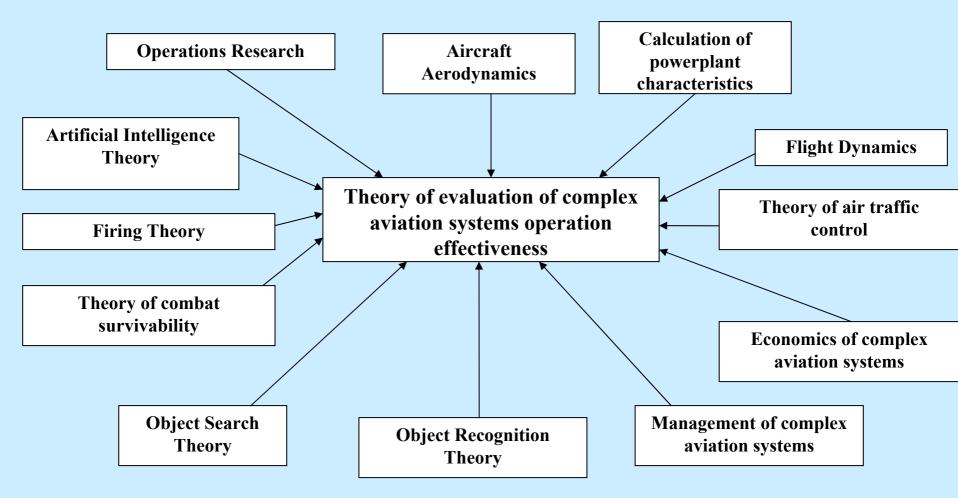
Modeling by methods of theory of evaluation of combat aviation systems operation effectiveness





Combat helicopter system

Theory of effectiveness evaluation is a complex subject

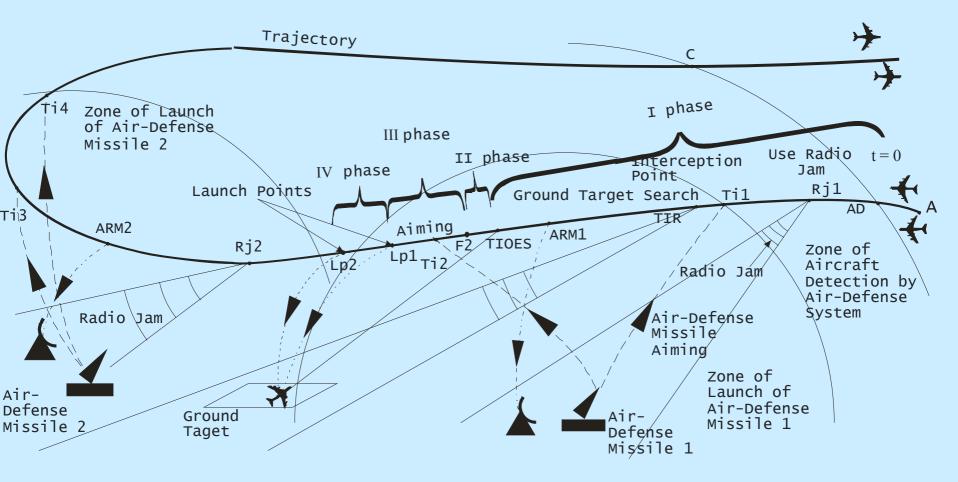


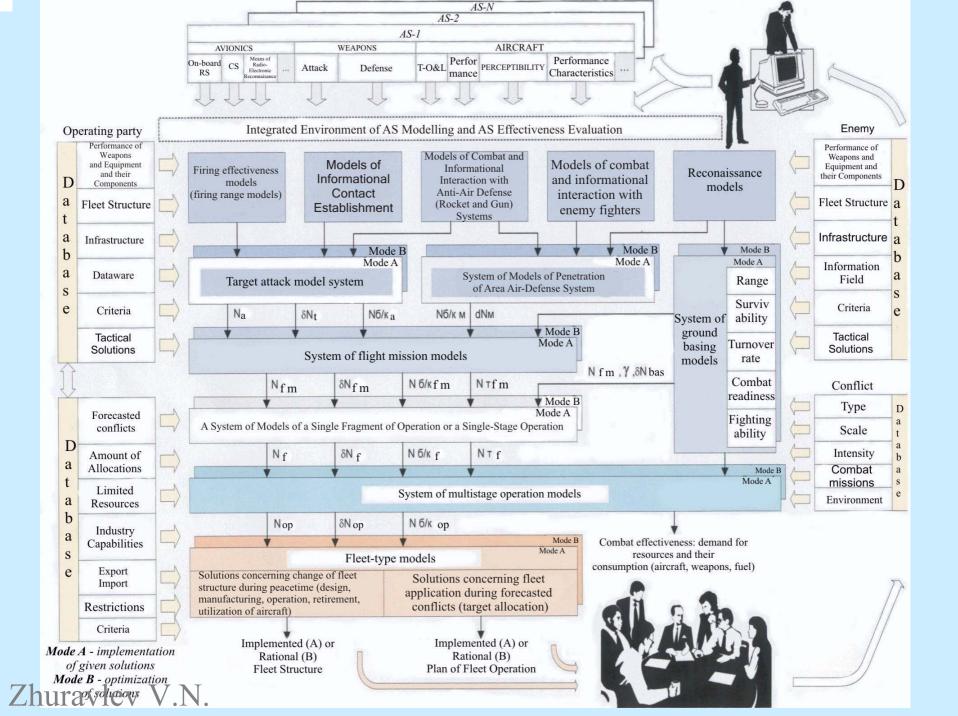
Initial data and results of comparison of two alternative Combat Aviation Systems

N⁰	Combat Aviation Systems Alternatives	1	2
	Main performance		
1	Maximum take-off weight, W_{t-o} , kg	6000	9500
2	Empty Weight, W_{empt} , kg	3300	5165
3	Maximum speed, km/h	300	300
4	Maximum rate of climb, m/s	12	8
5	Maximum load factor	4	3,5
6	Weight of equipment for combat survivability increase, kg	300	200
7	Maximum quantity of Anti-Tank Guided Missiles, n_{ATGM} ,	8	12
	Comparison Criteria		
1	Full Payload-to-Maximum Take-Off Weight ratio, <i>k</i> _{fpMTO}	0,45	0,456
2	Mathematical expectation of distribution of the number of targets, which will be hit during one attack (all missiles are fired within one target run), n_T	4,8	7,2
3	Losses of Combat Aviation Systems due to Anti-Aircraft Defense , $\Delta N_{aircraft}$ Ratio of hit targets to losses because of Anti-Aircraft Defense (all missiles are fired within one target run), $n_{T \ relative}$	0,4 12	0,53 13,5
4	The number of target runs (four missiles are fired within each target run) Mathematical expectation of distribution of quantity of targets, which are hit during all target runs Σn_T	2 2,5	3 4,5
Zhur	Losses of Combat Aviation Systems because of Anti-Aircraft Defense System during all target runs, $\Sigma\Delta N_{aircraft}$ Ratio of hit targets to losses because of Anti-Aircraft Defense system during all target runs, $\Sigma h_T \stackrel{\text{ev}}{\to} h_T$	0,45 5,6	0,96 4, 7

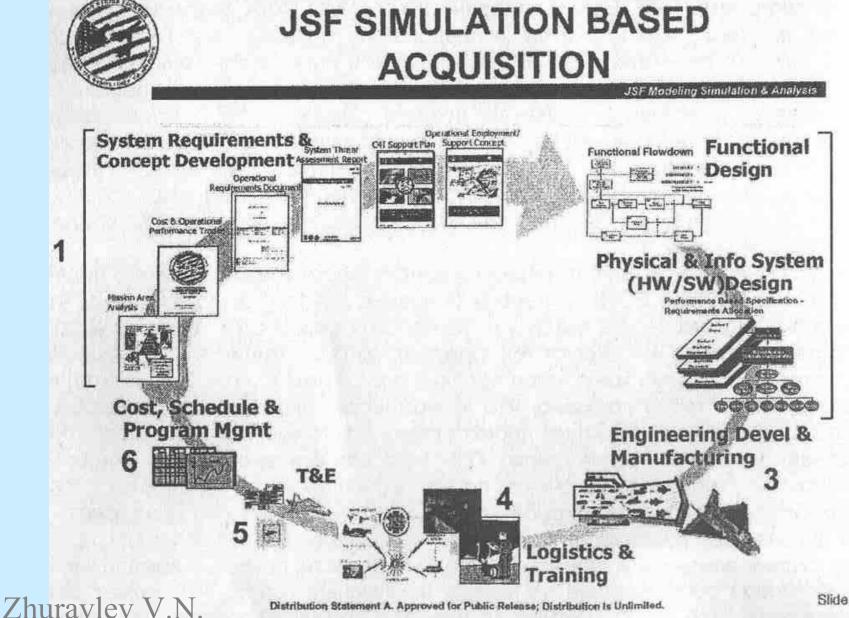
The presented above example of evaluation of effectiveness of Combat Aircraft Systems Operation has demonstrated the importance of application of methods and models of the theory of evaluation of aviation system operation effectiveness during design process.

Scheme of Aircraft Systems Group Attack





System Concept development in JSF program



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2

Various Coast-Guard Vehicles



Alternative PSRV types

PSRV Type	Seaplane Be-200	Ekranoplane "Orlenok"	Helicopter EH-101	VTOL V-22	Patrol vessel		
Take-off weight, kg	36000	125000	14280	21550	150000		
Cruise speed, km/h	610	350	250	510	70		
Range, km	3200	1100	1500	2500	3200		
The necessity of contact with water (water landing) during the evacuation of the people or setting down of the inspection group.	yes	yes	no	no	yes		
The on-board radar range, km.	100	25	100	100	20		
The length of liability zone of one PSRV during the PO accomplishment $L_{liabPSRV}$, km.	500	200	300	400	58		
The cost of one PSRV, \$ mln	29,4	44,5	5,9	11,5	-		

Patrol operation

The probability that the violator ship would not be arrested $P_{n/a}$ is the criterion of patrol operation:

$$K_2 = P_{n/a} \rightarrow \min.$$

The process of evaluation of the patrol operation effectiveness can be divided into two stages:

- **1-st stage**: Determination of:
- the necessary quantity of patrol and search-rescue vehicle bases (PSRVB) N_{PSRVB} ,
- the total patrol and search-rescue vehicle quantity N_{PSRV} ,
- the distribution of search-rescue vehicle bases in the region.
 2nd stage: Determination of the values of the effectiveness criterion K₂ for all types of vehicles.

Search and rescue operation

The critical values of the weather parameters, which should be taken into account during the calculations, and the appropriate ranges.

- 1. The lighting conditions: day; night.
- 2. The amount of cloudiness: clear or cloudy weather.
- **3. The wind velocity** V_w : $V_w < 16 \text{ m/s}$; $V_w > 16 \text{ m/s}$.
- **4. The wave height** H_w : $H_w < 1,25$ m; 1,25 m $< H_w < 3,5$ m; $H_w > 3,5$ m.
- **5. The water temperature** t_{water} **:** $t_{water} < 5^{\circ}$ C; $5^{\circ} < t_{water} < 12^{\circ}$ C; $t_{water} > 12^{\circ}$ C.
- 6. The air temperature t_{air} : $(t_{air} < 0^{\circ} \text{ C}; t_{air} > 0^{\circ} \text{ C})$.

The criterion of a search and rescue operation

The probability of the successful rescue operation over the whole zone and year is the criterion of operational effectiveness during a rescue operation K_1 . $\prod_{i=1}^{I} S_i \times P$

$$K_1 = \sum_{i=1}^{1} \frac{S_{P_i} \times P_i}{S_0} \longrightarrow \max$$

VTOL: The rescue probability P_i as a function of the distance r

Where:

 S_{pi} is the area where the rescue $\frac{1}{L}$ probability is equal to P_i ;

 S_0 is the area of the whole zone. The value of *the probability of the successful rescue of people* P_i depends on the distance r from base and is calculated by the formula:

$$P_{i} = \sum_{j=1}^{j=n_{W}} P_{rj} \times P_{dj} \times P_{j};$$

wave V.N.

L=100 km *L*=200 km *L*=300 km *L*=500 km

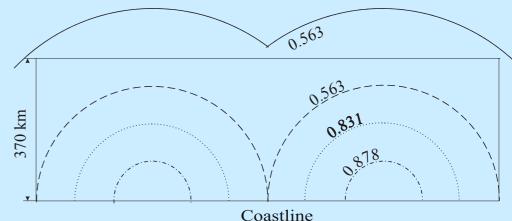
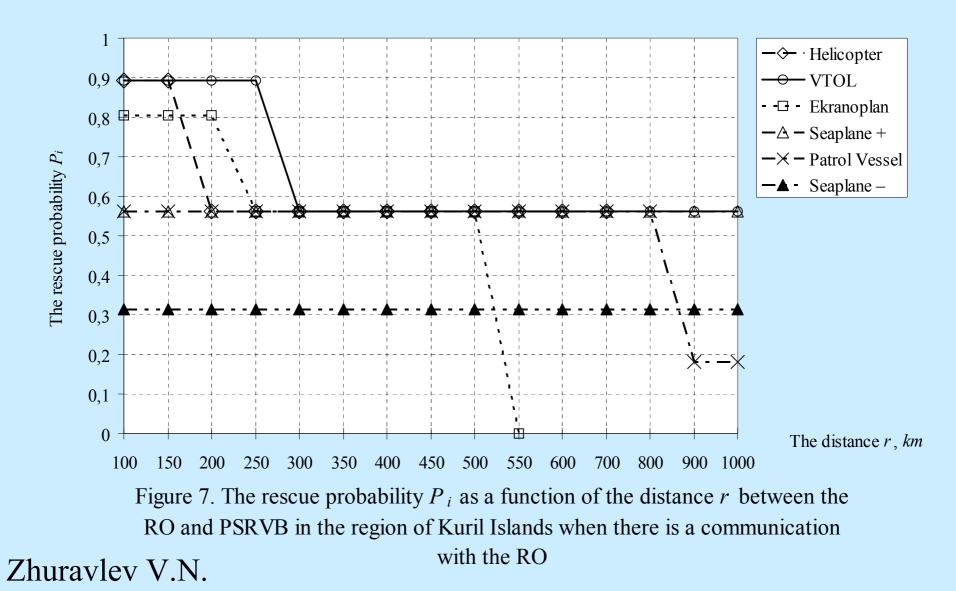


Figure 6.

Dependence of rescue probability on distance between RO and PSRVB



The dependence of probability that violator would not be arrested on cost of creation of CGS

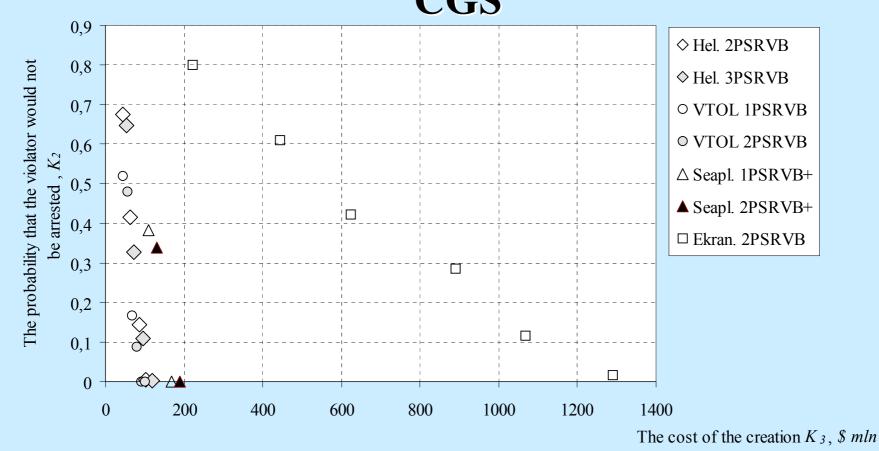
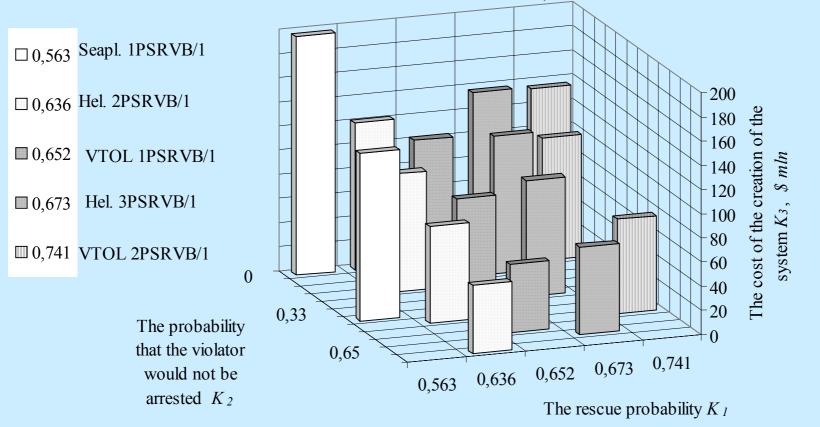


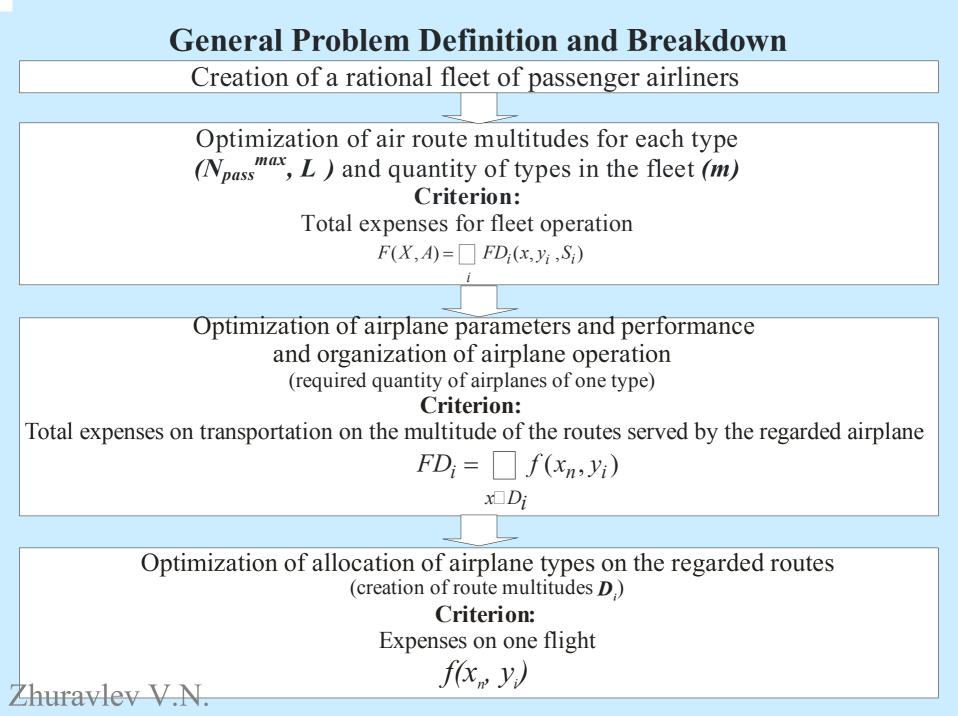
Figure 10. The probability that the violator would not be arrested K_2 as a function of the cost of creation of the CGS air component K_3 (the region of Kuril Islands)

Figure 11. The rescue probability K_1 and the probability that the violator would not be arrested K_2 as functions of cost of creation of the CGS air component K_3 (the region of Kuril Islands, the information about RO location is available all the time).



Creation and Optimization of Multi-Type Airliner Fleet



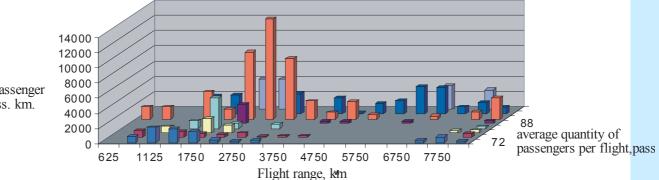


Initial data

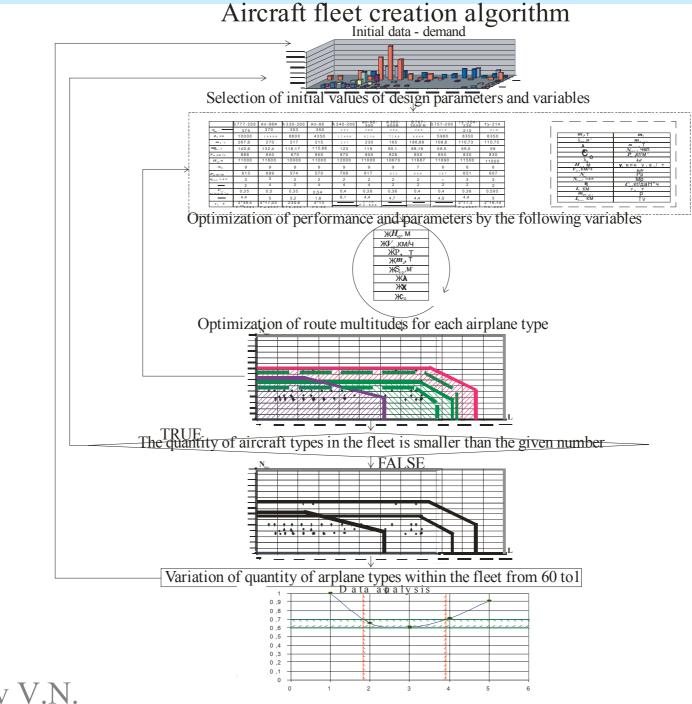
Dependency of passenger flow (mln.pass km)depending on range of air passenger transportation and average quantity of passengers per flight

		250-500	-			R	ange	of pas	senge	r air t	ransp	ortati	on , kn	n			-			
-	0-250	250-500	500-750	750-100	1000-1250	1250-1500	1500-2000	2000-2500	2500-3000	3000-3500	3500-4000	4000-4500	4500-5000	5000-5500	5500-6000	6000-6500	6500-7000	7000-7500	7500-8000	more than 8000
0-6	41	119	134																	
6-10	24	24	273	131																
10-14		41	139	319	115															
14-18		27	114	- 96	458	583														
18-22		33	65		110	174	1339													
22-26			105	152	91	216	716	1230												
26-30		50	132	282		202	282	897	1150											
30-34		39	36	76		47	154	58	1186	898										
34-38		64	47	136	50		118	137	156	1298	461									
38-42			171	129	53	121	390	220	83		946	342								
42-46			207	82	64		292	422	196	317	114	838	220							
46-50			454	225	222	77	81			231		137	901	257						
50-54			422	205	83	84	180	365	332	249				552	180					
54-58				192	718	108	309	104	117		152				419	427				
58-62				476	575		455			147					196	248	400			
62-66					1003	588	355	463		304	163						755	273		
66-70					290	842	1413	403	427									401	517	
70-74				810	1970	1751	1368	359	174	335								273	744	188
74-78				910		722	537	404	609	198	207	209								518
78-82					862		1916	998											300	331
82-86						1003	3995	649		529										268
86-90								2519				287	292			316				380
90-120			1580	1600		3604	1318	8798	13172	7972	2316	842	2257	579			384		910	2800
120-150						2356	2564			2709		2167	125	1412	1744	3674	3509	954	1575	918
150-200								4044	4056								3151		2601	

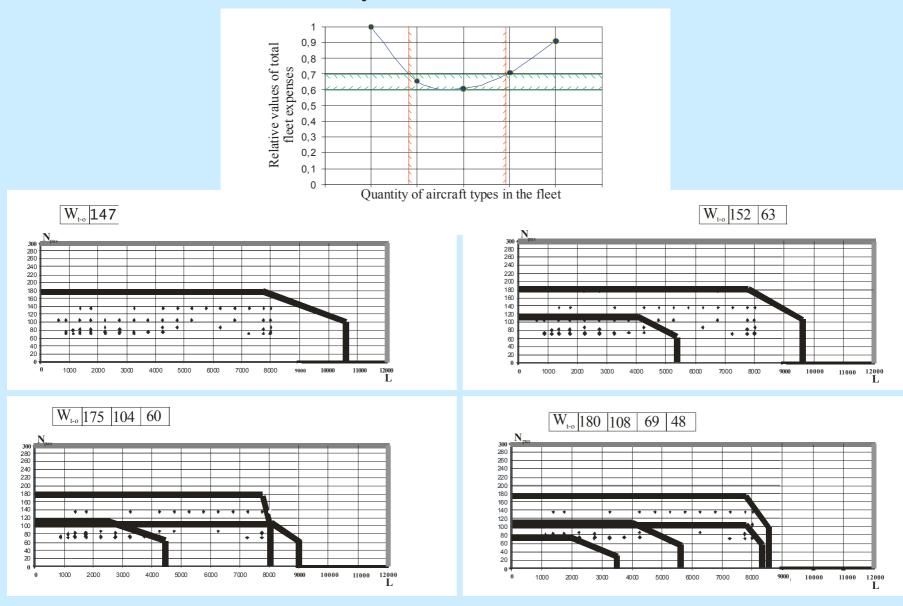
Dependency of passenger flow (mln.pass km)depending on range of air passenger transportation and average quantity of passengers per flight



Average annual passenger flow, mln. pass. km.



Analysis of the derived data



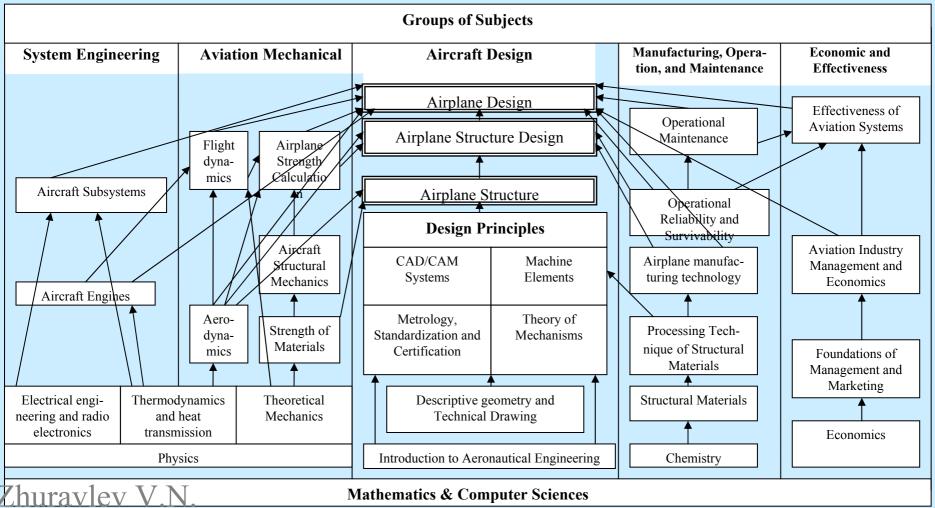
Department of Design and Operational Effectiveness of Complex Aviation Systems of Moscow Aviation Institute (MAI)

The department was founded more than 30 years ago;

- We teach specialists in the field of Design and Operational Effectiveness of Complex Aviation Systems;
- The specialists work in:
- aircraft design companies
 - Chief Designer Departments,
 - Departments of Operational Effectiveness,
 - Conceptual Design Departments ;
- Civil and Military Aviation Research Centers;
- Airline Companies.

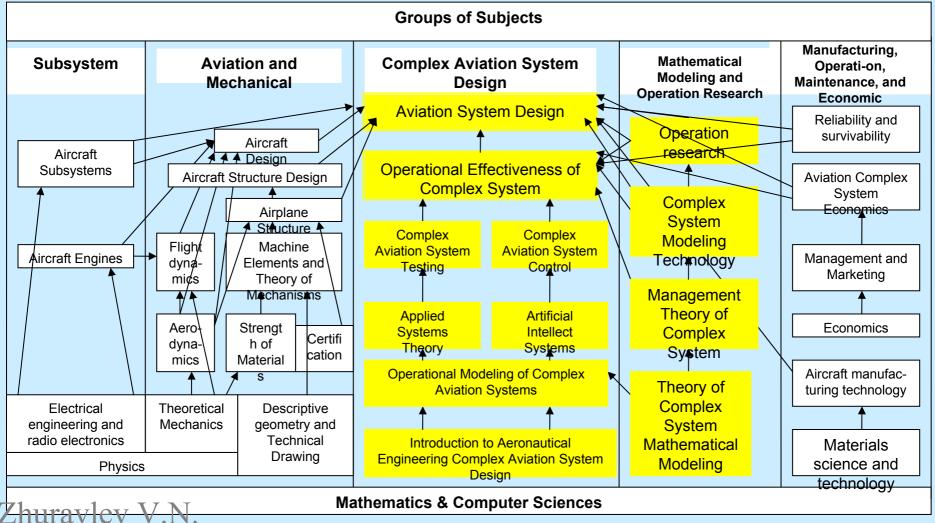
The curriculum structure for specialty "Airplane **Design**" (Engineers (Masters) Degree in MAI)

(without liberal arts)



Mathematics & Computer Sciences

The curriculum structure for specialty "Design and **Operational Effectiveness of Complex Aviation** Systems" (Engineers (Masters) Degree in MAI) (without liberal arts)



Mathematics & Computer Sciences