<u>CEASIOM</u> <u>Improving the Tools for Aircraft</u> <u>Conceptual Design</u>

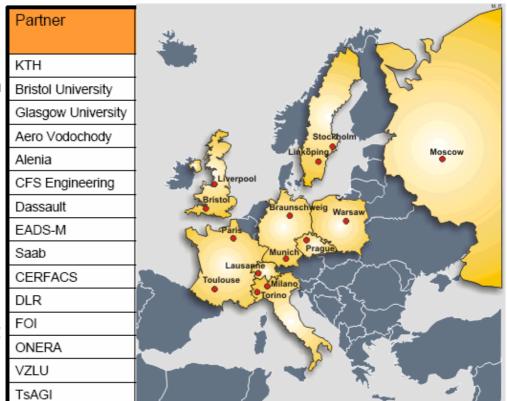


- SimSAC project
- QCARD and its improvements
- Automatic CAD solid model generation
- Tests and assessments of design process



The Vision, Mission, Motivation & Consortium

- Vision A simulation tool for Stability & Control analysis in the conceptual design process with higher fidelity than current methods
- Mission Build and assess a simulation tool for S&C analysis in conceptual aircraft design with quantifiable uncertainty
- Motivation Standard aerodynamic data models in conceptual design provide too low-fidelity characteristics, which introduces mistakes in the Flight Control System. Correcting these mistakes later in design is very costly



See http://www.simsacdesign.org



The Problem in Conceptual Design

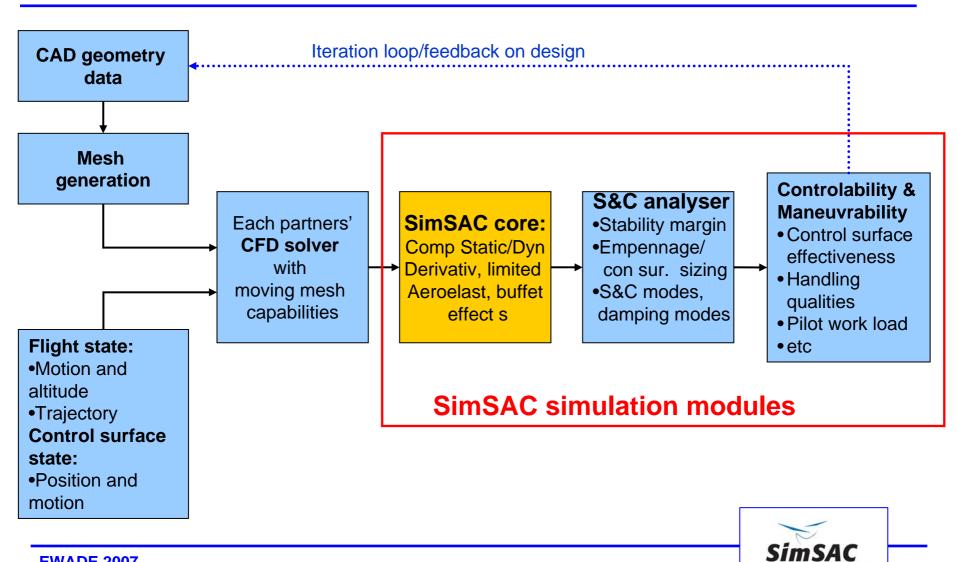
The simplified methods used in the early phases of design do not give sufficient fidelity, which may result in mistakes which are costly to correct later in the design cycle.

Some examples pertaining to the Flight Control System are:

- DC-9: unexpected pitch-up and deep stall of T-tail lead to costly redesign
- DC-9-50 & MD-80: inadequate directional stiffness at high angles of attack in sideslip; adoption of low-set nose strakes
- **SAAB2000**: larger than expected wheel forces caused delay in certification; costly redesign of elevator control system
- **Boeing 777**: missed horizontal tail effectiveness led to larger than needed horizontal tail



SimSAC simulation modules in broad terms



SimSAC project

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Simulation Environment: CEASIOM

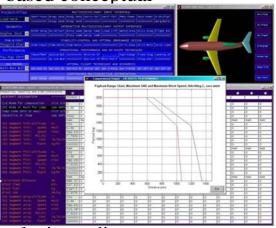
<u>Computerised Environment for Aircraft Synthesis and Integrated</u> Optimisation <u>Methods</u>

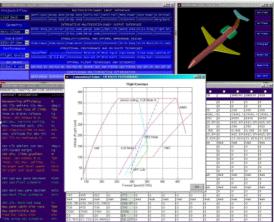
- Architecture, design integration and analysis tool
- QCARD Quick Conceptual Aircraft Research & Development
 - User-interactive MATLAB-based conceptual

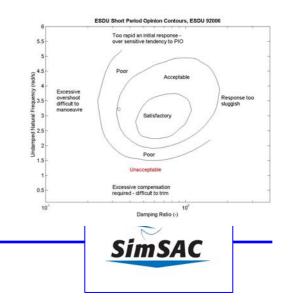
design package

Tailor-made to predict, visualise and assist in optimising designs

- 9 sub-spaces coupling
 Permit trade-studies
 and risk assessment
- CAD system integration
 - MVO/MDO visualisation-analysis medium
 - Can interface with sizing decision support modules
- Incorporate quantifiable uncertainty, robustness & modularity to solution synthesis process

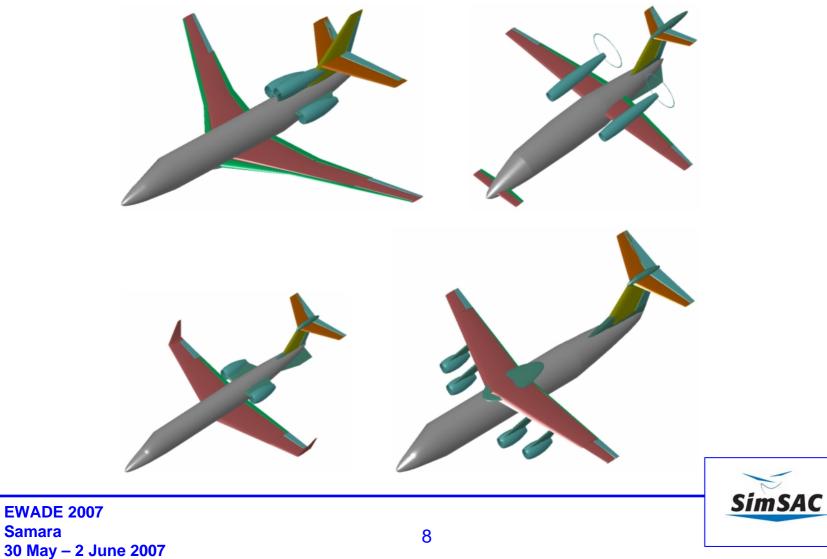






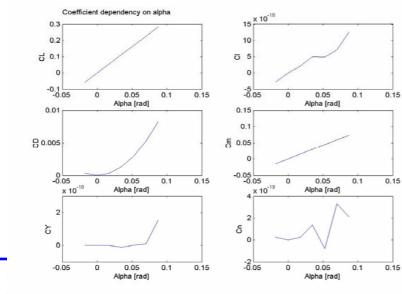
Examples of geometries in QCARD

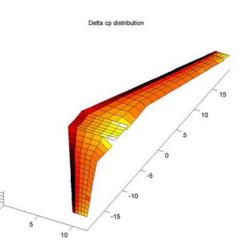
Samara



Unsteady TORNADO - TORNADO

- Vortex lattice program developed by Tomas Melin at the division of aeronautics of the Royal Institute of Technology KTH, Stockholm
- Computation of lift, drag and moments coefficients in a steady case
- Widely used: Virginia Tech (US), Loughborough University (UK), Sao Paulo University (Brazil), Saint Cyr (France), Northwestern University of Polytechnology (China)

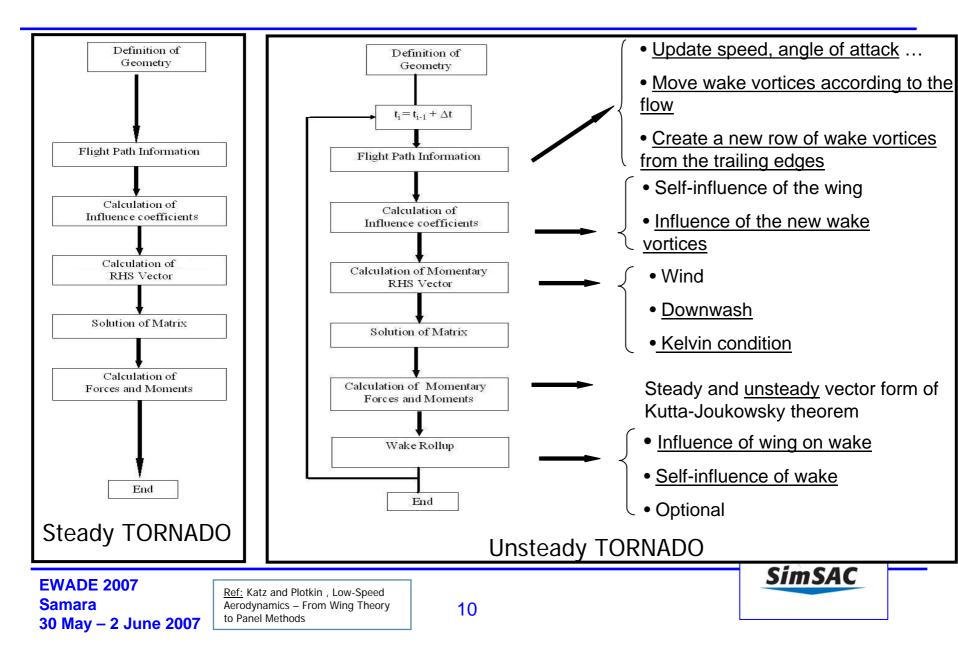




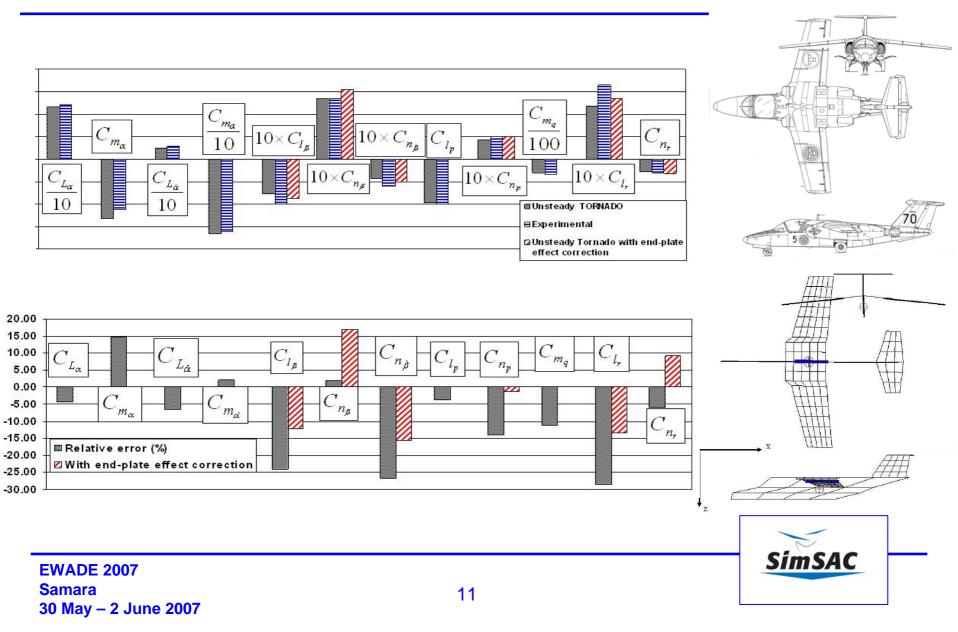
| TORNADO CALCULATION RESULTS | | | | | | | | |
|-----------------------------|--------------|---------|-----------------------|-------------------|-----------|------------------------|--------------|--|
| JID: | | q1 | | Downwash matrix o | ondition: | | 11.9374 | |
| Reference area: | | 12.0714 | | | | | | |
| Reference chord: | | 1.5451 | | | | | | |
| Reference span: | | 9 | | | | | | |
| Net Wind Forces: (Nm) | | | Net Body Forces: (Nm) | | | Net Body Moments: (Nm) | | |
| L: 332.4018 | | | Z: | 331.459 | | Pitch: | -726.1043 | |
| D: 7.1904 | | | X: | -5.7027e-015 | | Yaw: | -4.9462e-014 | |
| S: -5.7027e-015 | | | Y: | -26.0303 | | Roll: | -1.8862e-013 | |
| | | | | | | | | |
| CL | 0.44957 | | CZ | 0.4483 | | Cm | -0.63559 | |
| CD | 0.009725 | | СХ | -0.035206 | | Cn | -7.4331e-018 | |
| CY | -7.7128e-018 | | cc | -7.7128e-018 | | CI | -2.8345e-017 | |
| | | | | | | | | |
| STATE: | | | | | | | | |
| alpha: | 5.7296 | P: | | 0 | | | | |
| beta: | 0 | Q: | | 0 | Rudder s | etting [deg | 1]: | |
| Airspeed: | 10 | R: | | 0 | | | | |
| Density: | 1.225 | | | | | | | |

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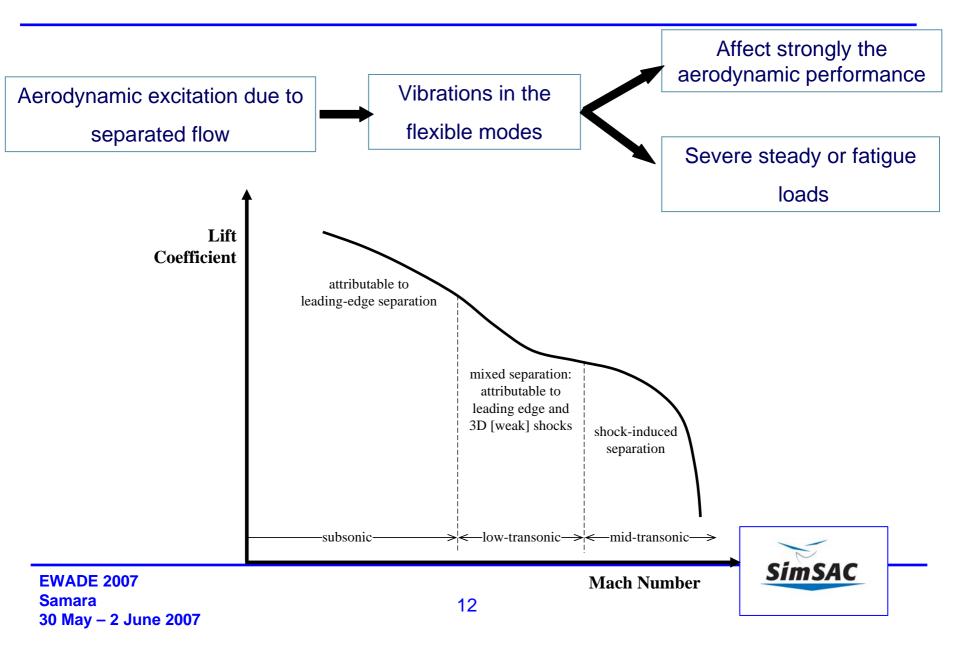
<u>Unsteady TORNADO</u> – Resolution loops



Unsteady TORNADO: SK105 benchmark



Buffet onset prediction - Buffet



Buffet onset prediction: summary of results

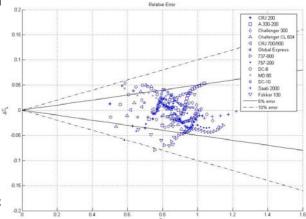
- Combination of simple sweep theory and fractional change theory
- Six influencing parameters:

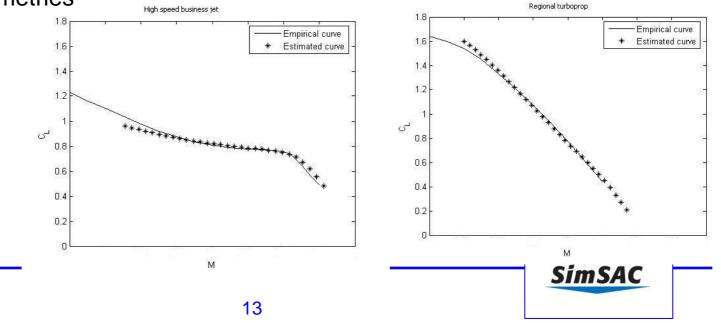
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- Reference wing planform: aspect ratio, taper ratio, quarter chord sweep
- Tip airfoil section: camber, thickness to chord, chordwise position of maximum thickness to chord
- Accurately predicts buffet for a very wide variety of airplane geometries

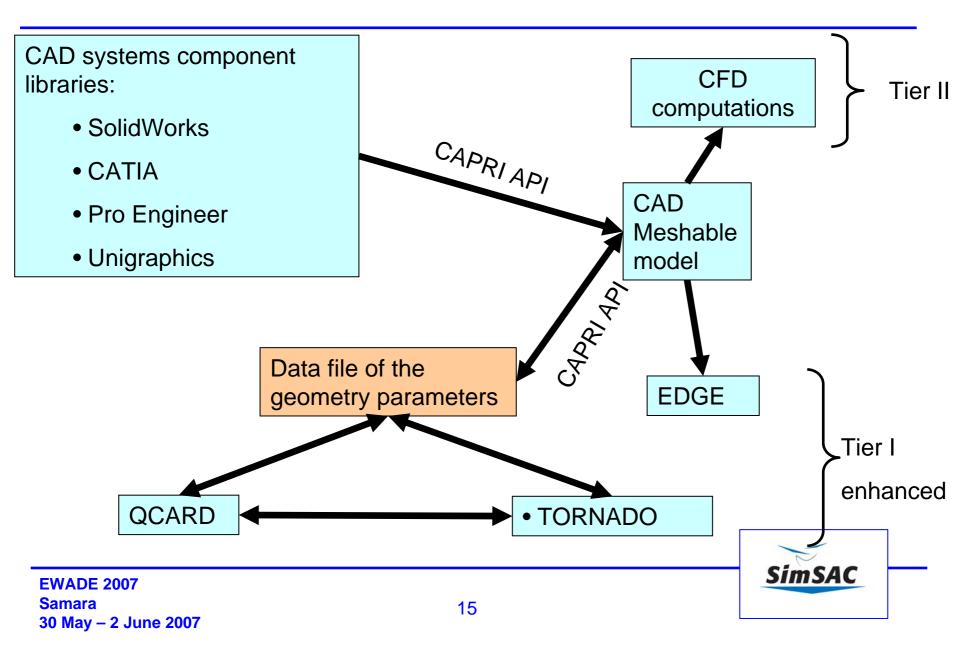




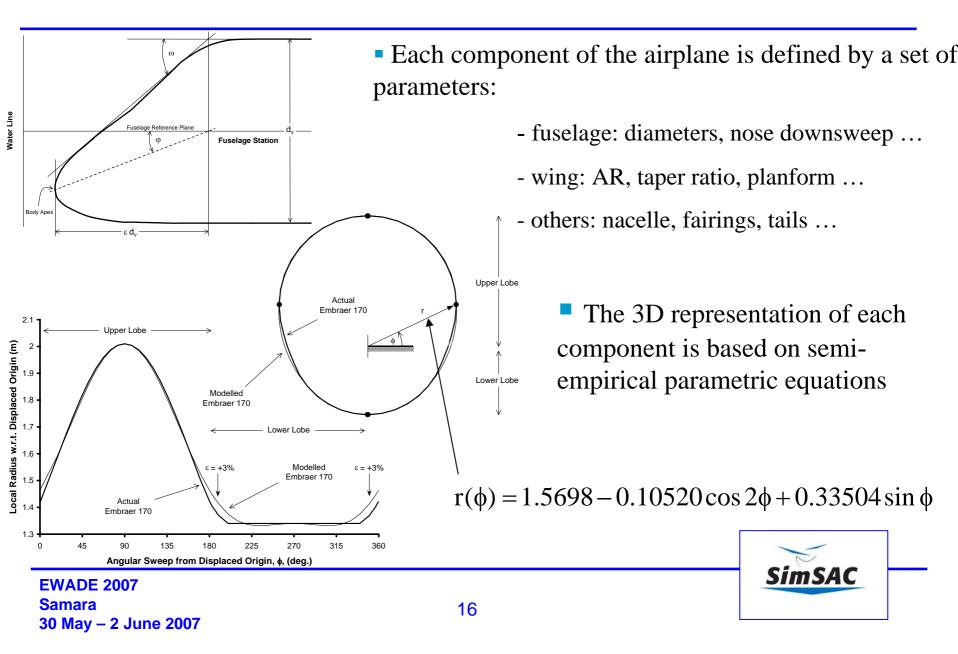
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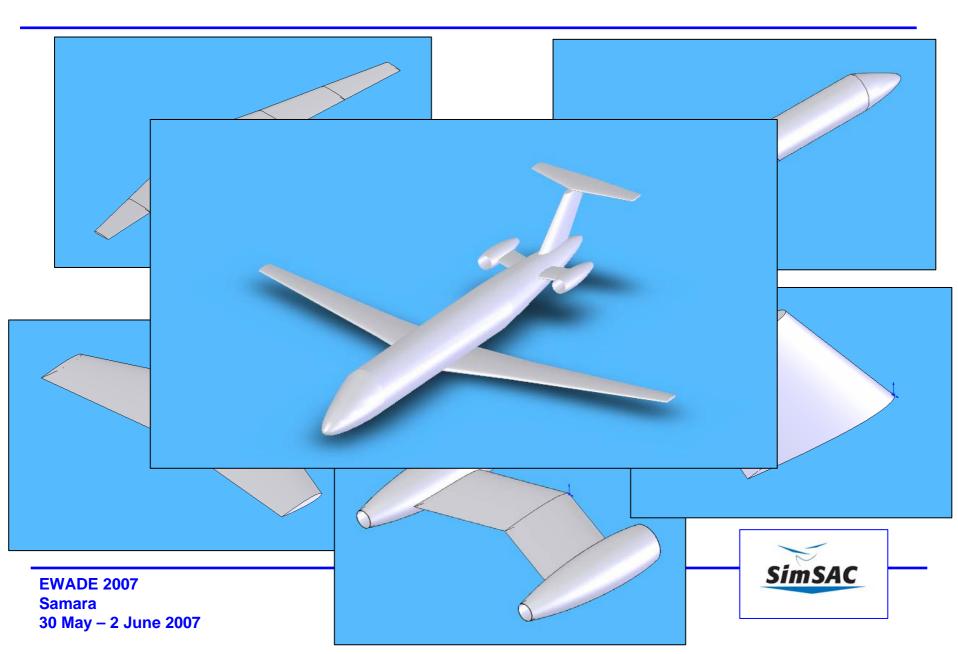
Master model concept



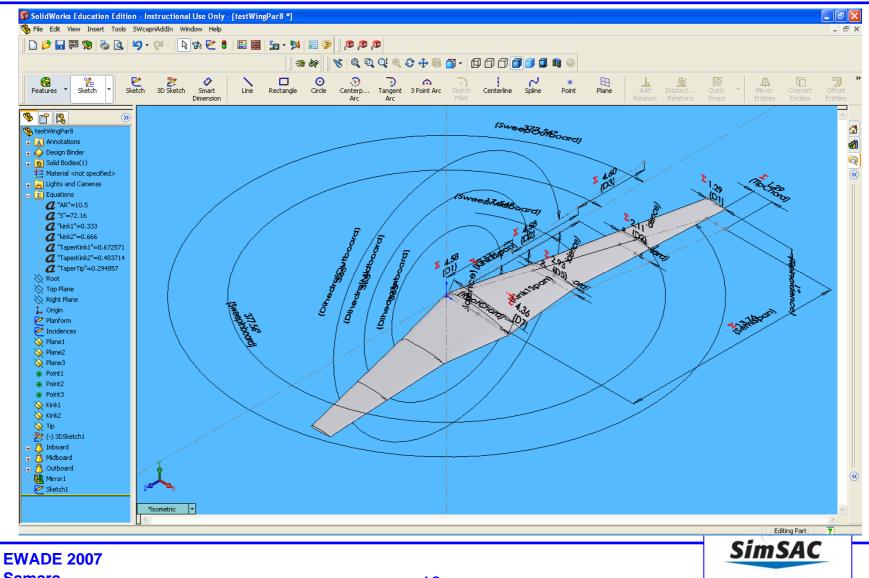
Parametric representation of airplanes in QCARD



Library of components

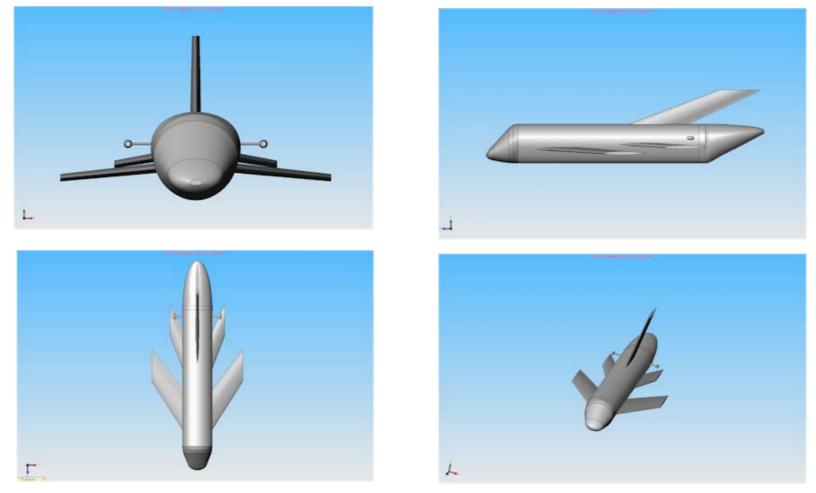


Parametrized wing in the CAD system



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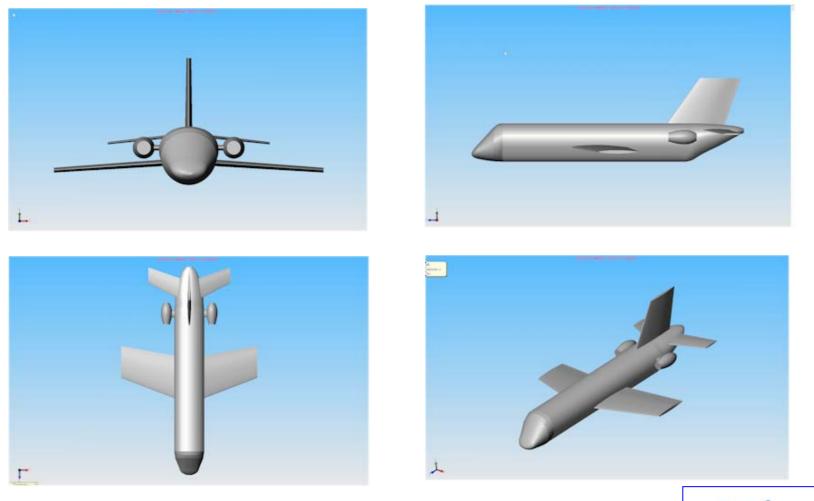
CAD exercise using SolidWorks





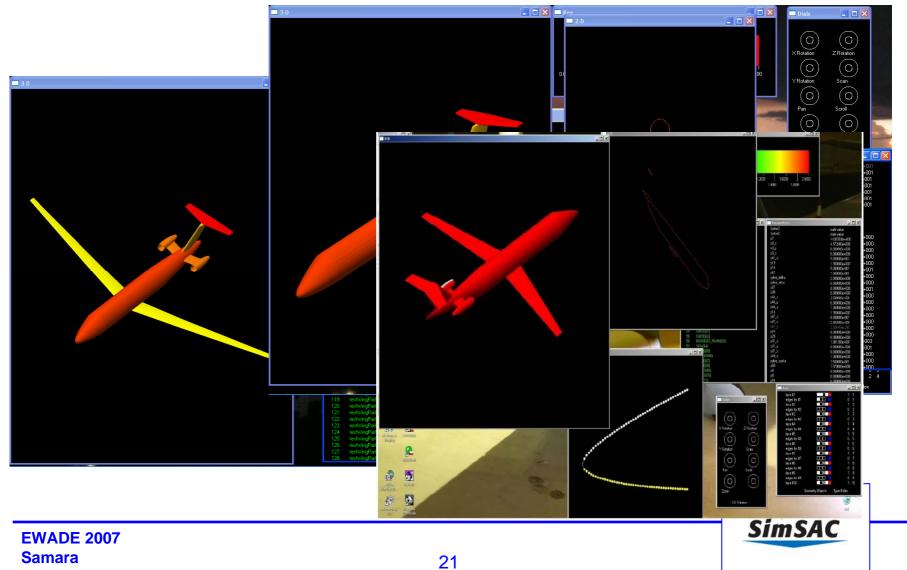
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CAD exercise using SolidWorks



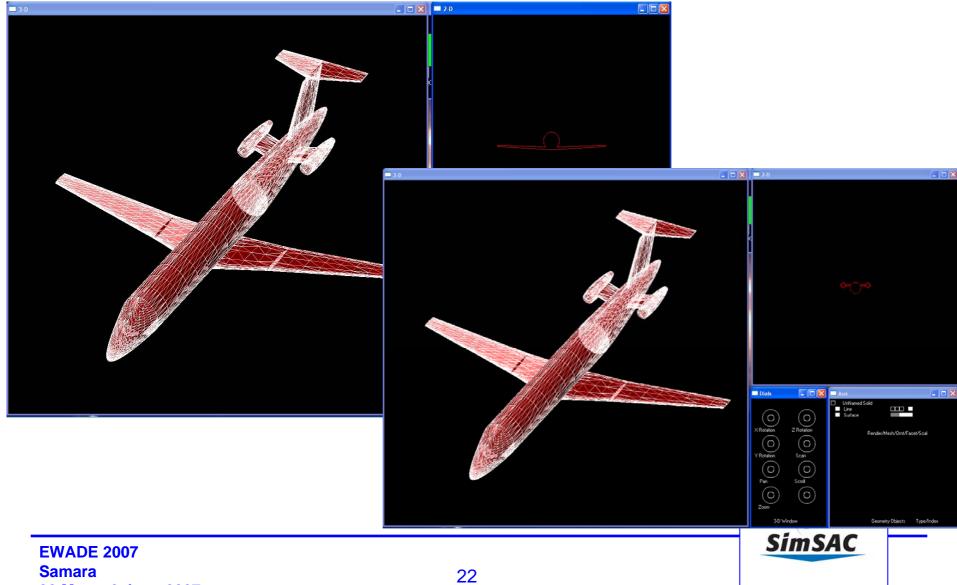
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CAPRI API and « Master » function



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CAPRI Tesselation and Boolean operation



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Design exercise: Transonic Cruiser

Design Specification for TCR (TransCRuiser)[1]

Class pitch 44" width 19" (2+2 seats),

70 Business Class pitch 38" width 19" (3+2 seats), and 80 Economy Class pitch 36" width 19" (3+2 seats).

Baggage and freight in LD3-46W containers. Possibility to divide into Three Classes:

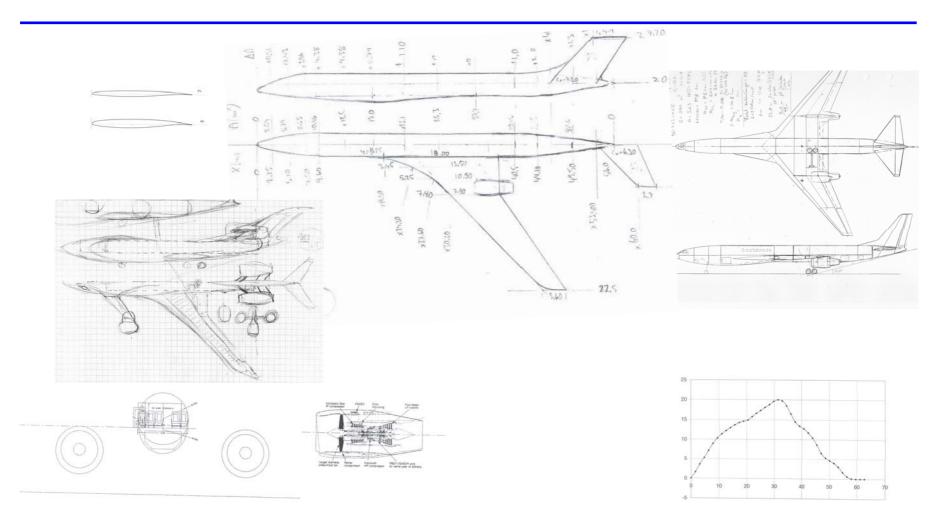
Cabin and Crew: Six lavatories and two galleys with a total of 40 full size trolleys. Two pilots and six cabin attendants. Range: 5,500 nm, followed by 250 nm flight to alternate and 0.5 hour loiter at an altitude of 1.500 ft. Additional 5% of block fuel. Design cruise speed: MD = 0.97 at greater or equal to 37,000 ft. Climb: Direct climb to FL370 at max WTO. Take-off and Landing: TO distance 2,700 m at an altitude of 2,000 ft, ISA +15 and max WTO. Landing distance 2,000 m at an altitude of 2,000 ft, ISA and max WL with max payload and normal reserves. Cruise @ h>=37,000 ft, M0.97 Powerplants: Two Turbofans. Pressurization: According to EASA. Noise requirement: According to ICAO. Decent Climb to FL370 Certification Base: **JAR25**. Loiter 0.5 h Fly to alternate 250 nm Startup, Taxi, Take-off [1] Based on AEA Long Range Requirements. Landing, Taxi, Shutdown SimSAC **EWADE 2007**

Nominal design for 200 PAX in Economy Class pitch 36", 22,000 kg max payload.

Pavload:

20 First

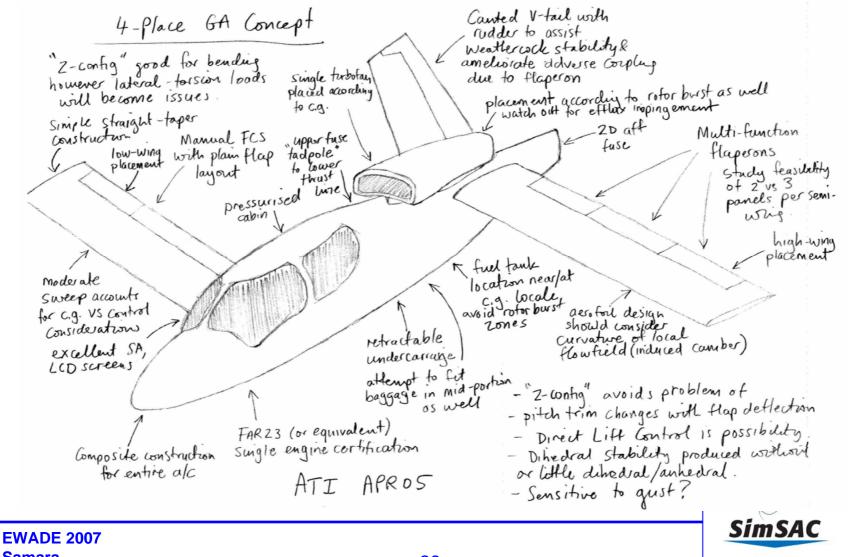
Design exercise: Transonic Cruiser





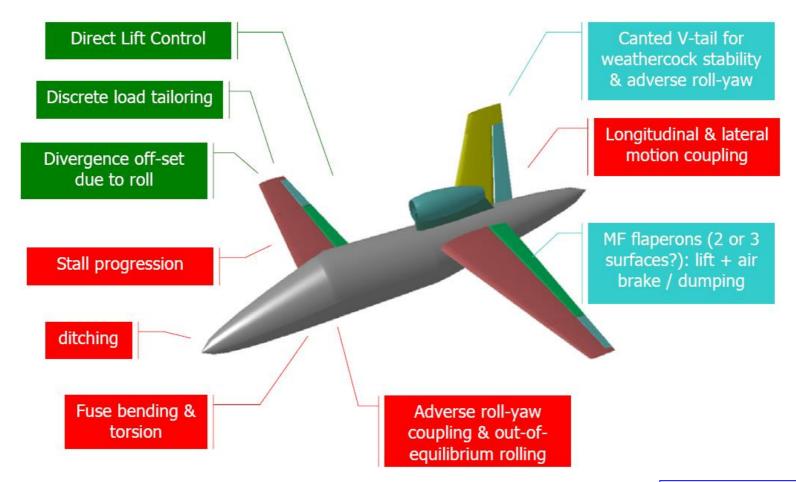
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Design exercise: Z configuration



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Design exercise: Z configuration



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